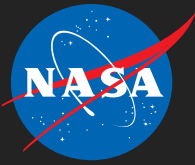




# MSFC ADVANCED CONCEPTS OFFICE DEFINING THE FUTURE OF SPACE EXPLORATION



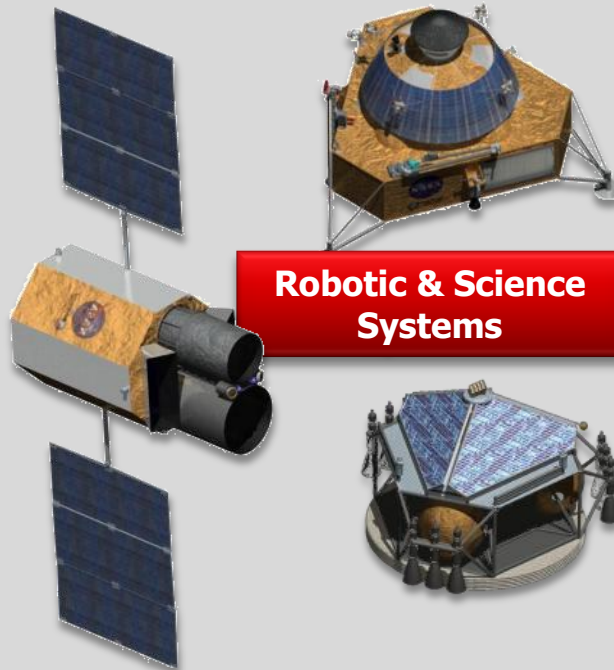


# Advanced Concepts Overview

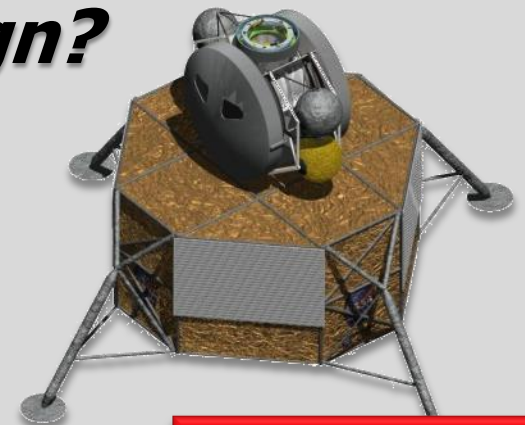
***We answer the questions:  
Will it work?  
What will it look like?  
What is the preliminary design?***



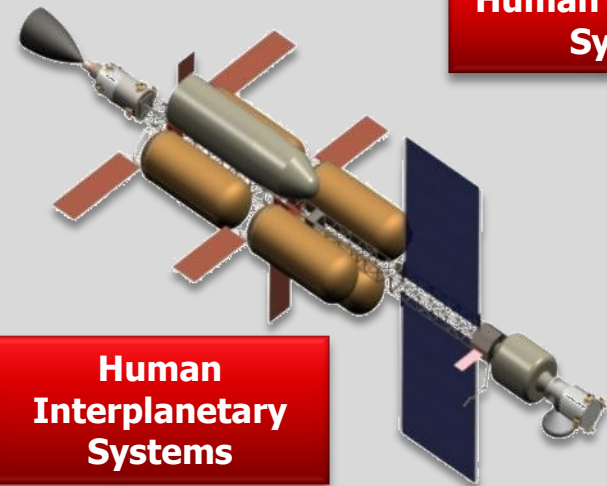
**Launch Vehicle Systems**



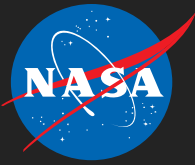
**Robotic & Science Systems**



**Human Exploration Systems**

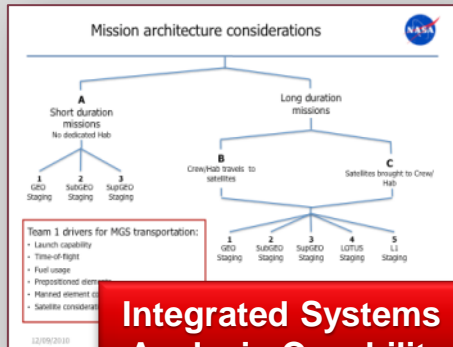


**Human Interplanetary Systems**



# Advanced Concepts Overview

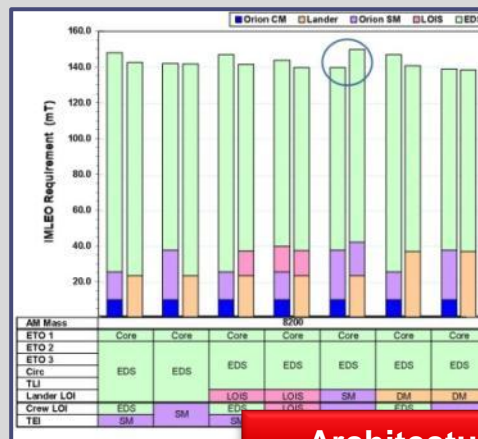
***We Utilize Multi-Disciplined Teams Within the Office to Provide Fully Integrated Assessments of Missions and Their Elements***



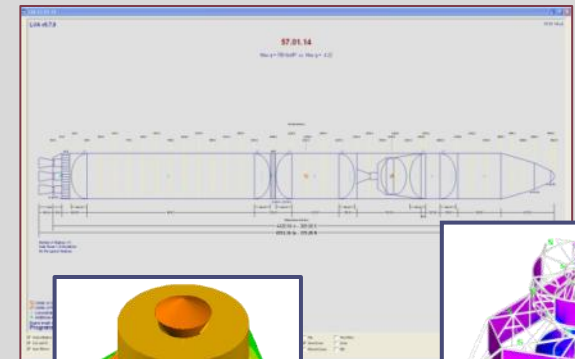
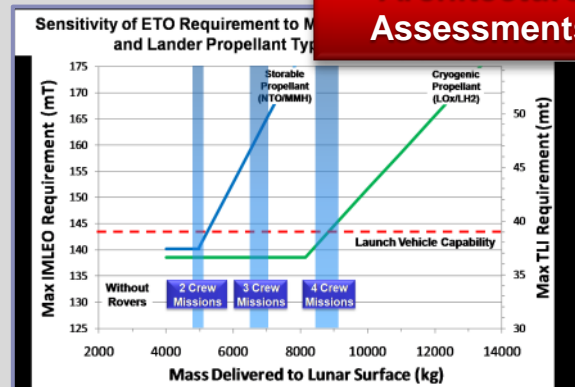
**Integrated Systems Analysis Capability**



**Mission Analysis**

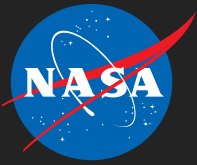


**Architecture Assessments**



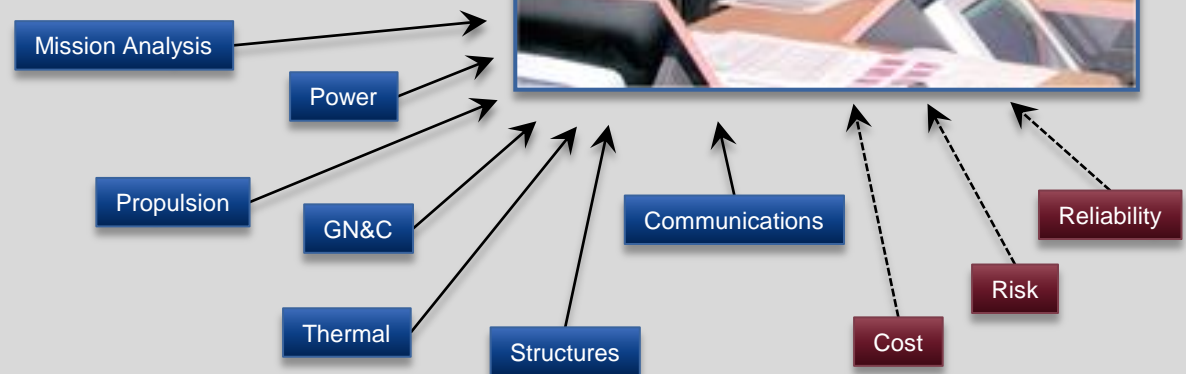
**Subsystem Design & Analysis**

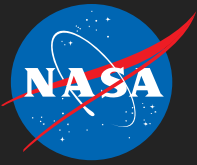




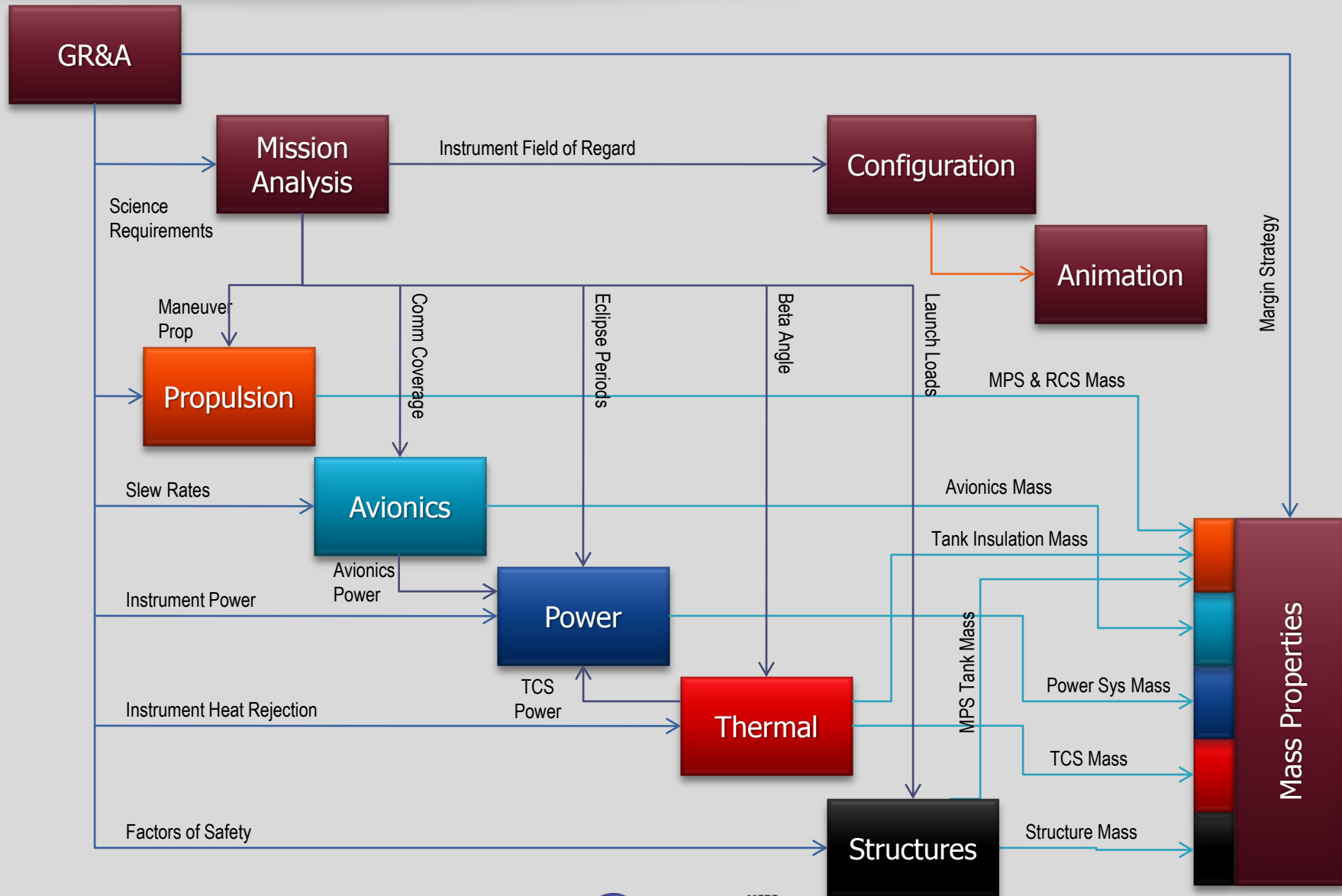
# Collaborative Design Team

- ◆ The ACO Design Teams are established, co-located teams of systems and design engineers
- ◆ Other disciplines or specific expertise are matrixed into the team as necessary
- ◆ Scientific Areas of Interest
- ◆ Programmatic Support
- ◆ Additional Discipline Support

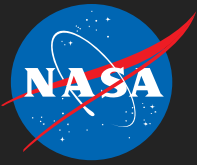




# Simplified Vehicle Definition Process







# ACO Contributions to the Agency

HEOMD

HAT

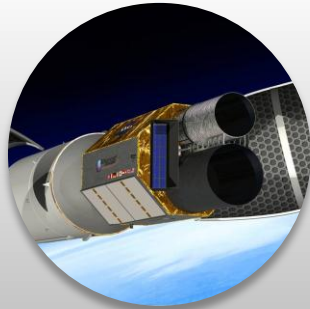
MSFC Center  
Development

MSFC Engineering  
Directorate

MSFC Science &  
Mission Systems



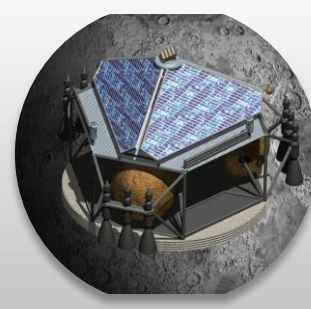
*Earth-to-Orbit  
Transportation  
System Definition*



*Earth & Planetary  
Science Concept  
Definition*



*Human Exploration  
Architecture  
Definition*

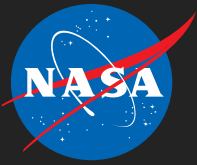


*Scientific & Robotic  
Exploration*

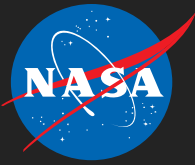


*In Space Element  
Definition*

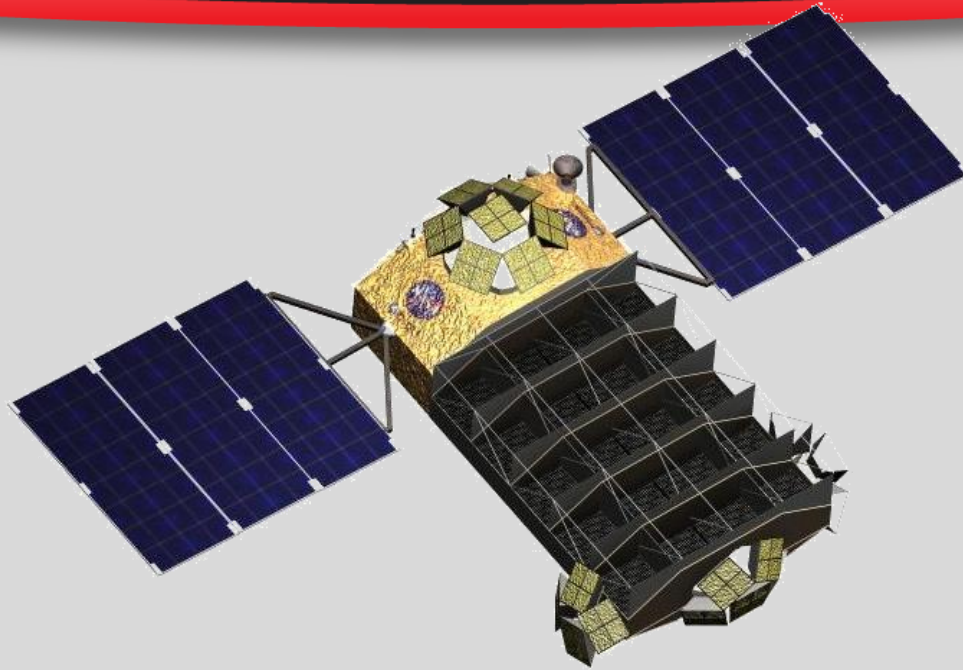
***Advanced Concepts Products Influence  
NASA Programs***



# STUDY EXAMPLES

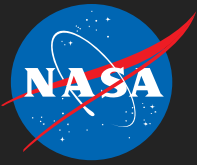


# AXTAR: Introduction



- ◆ The Advanced X-ray Timing Array (AXTAR) is an X-ray observatory concept combining very large collecting area, broadband spectral coverage, high time resolution, highly flexible scheduling, and an ability to respond promptly to time-critical targets of opportunity.
- ◆ It's mission is to probe the physics of ultra-dense matter, strongly curved space-times, and intense magnetic fields.
- ◆ Instruments: (1) the Large Area Timing Array (LATA) is for timing observations of accreting neutron stars and black holes; (2) the sensitive Sky Monitor (SM) acts as a trigger for pointed observations of X-ray transients and also provides sensitive monitoring of the X-ray sky.

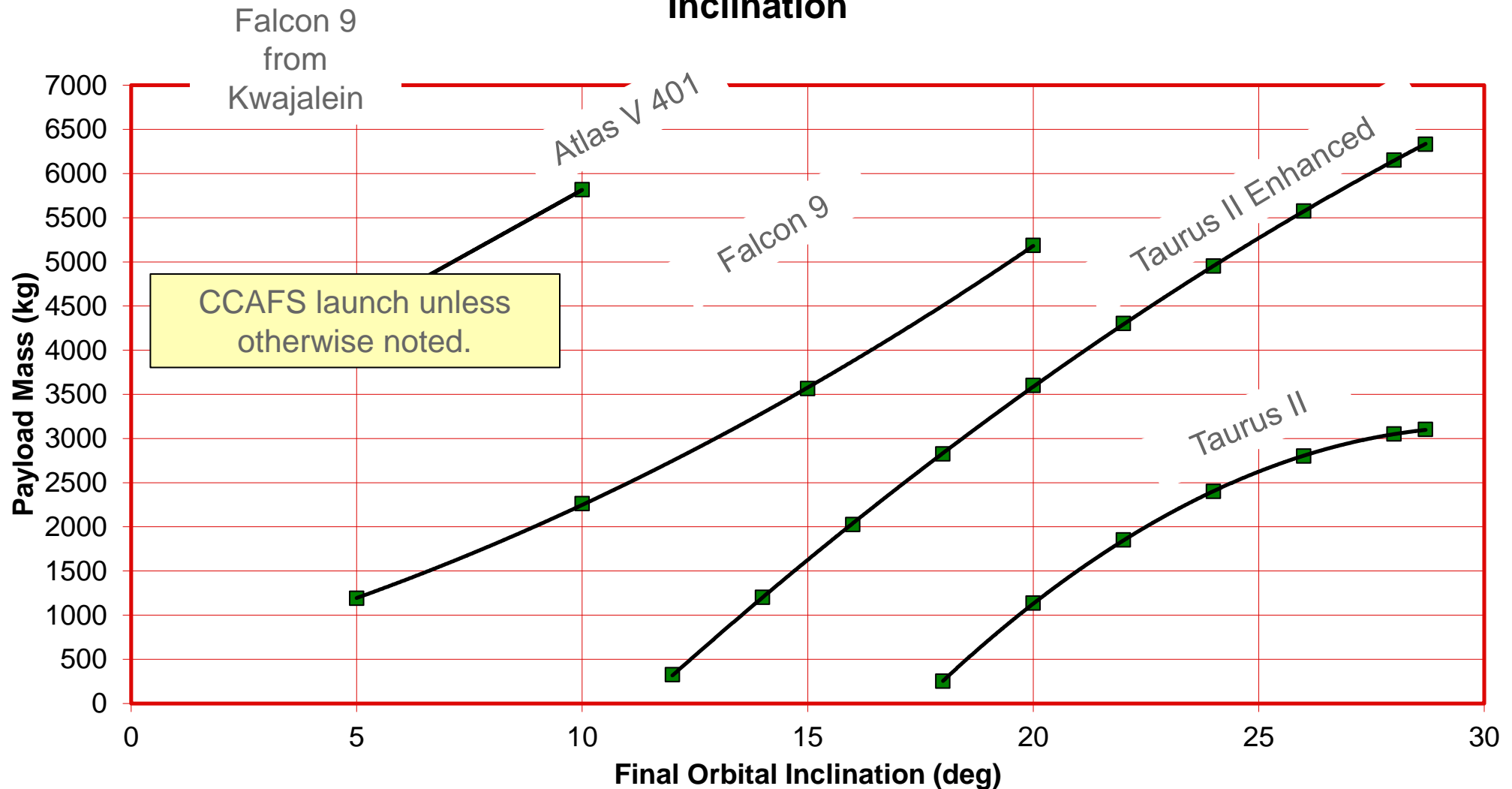




# Mission Analysis

## Launch Vehicle Performance (2/2)

### Launch Vehicle Performance to 600km Circular vs. Final Orbital Inclination

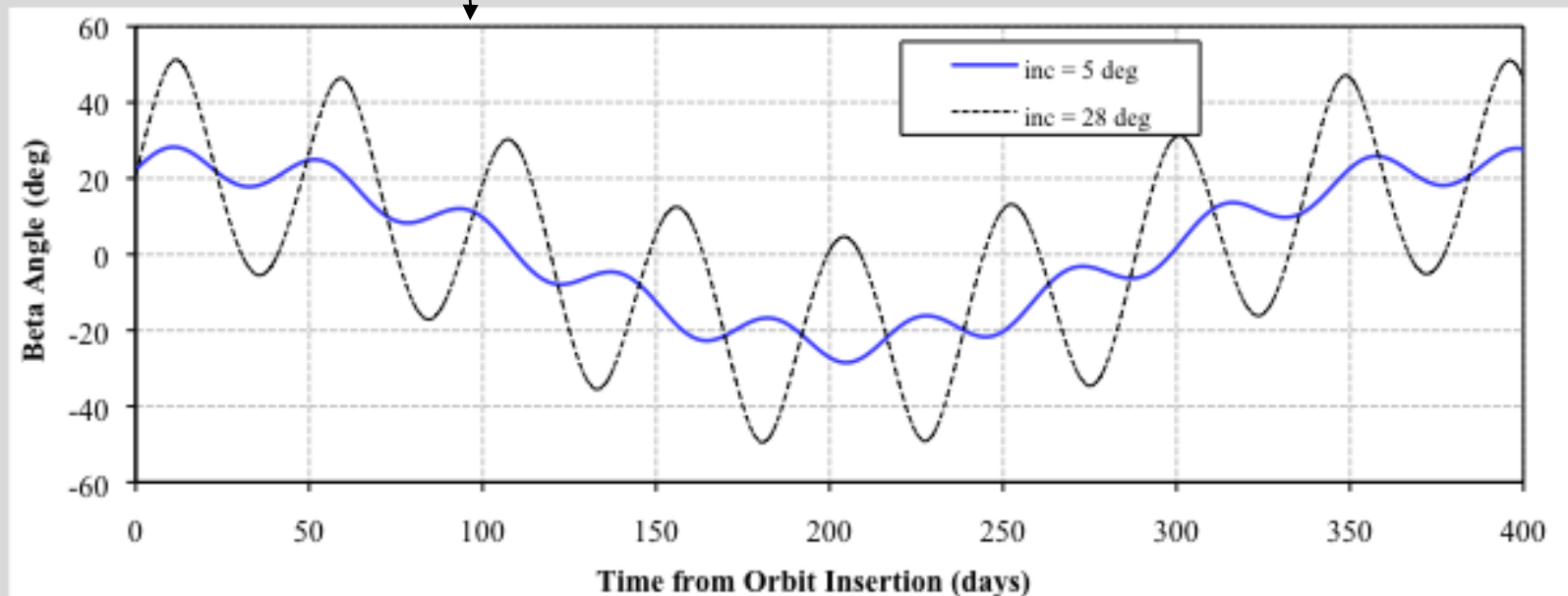
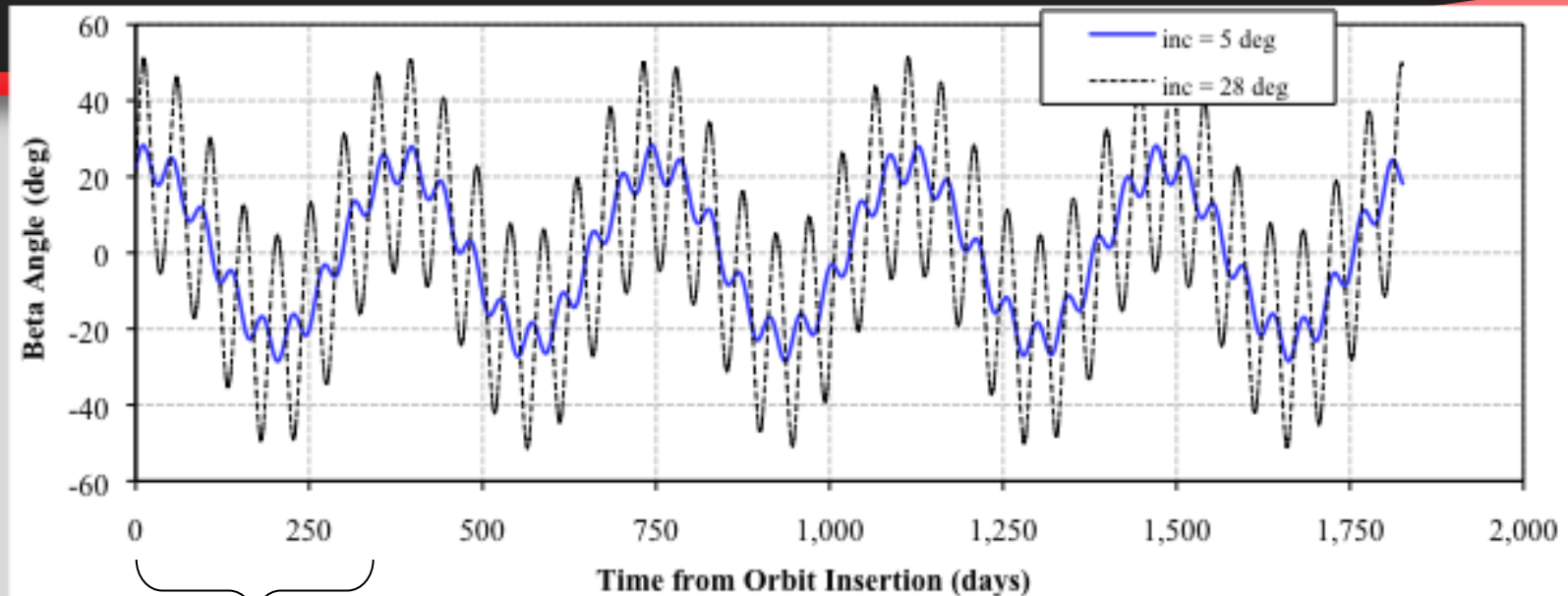


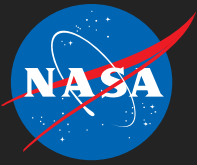
Spacecraft mass will determine final inclination.



# Mission Analysis

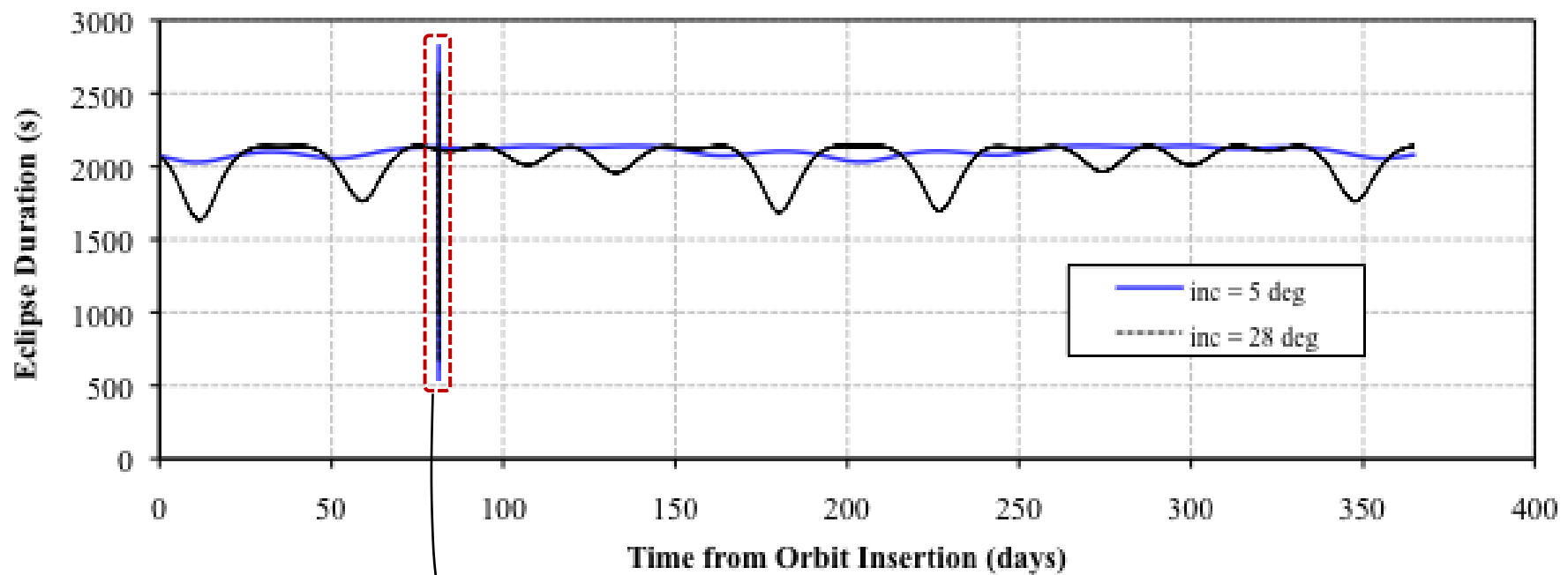
## *Beta Angle Histories*





# Mission Analysis

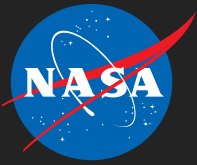
## Eclipse Durations



### Eclipses by Moon

Time from Insertion (days)	Duration (s)	Time from Insertion (days)	Duration (s)
$(i = 5^\circ)$		$(i = 28^\circ)$	
81.20	533	81.20	674
81.26	708	81.30	2636
81.30	611	81.40	998
81.31	1199		
81.37	655		

*Upon further investigation, shadowing due to lunar eclipses are only partial (i.e. penumbra) and, therefore, can most-likely be neglected.*



# Mission Analysis

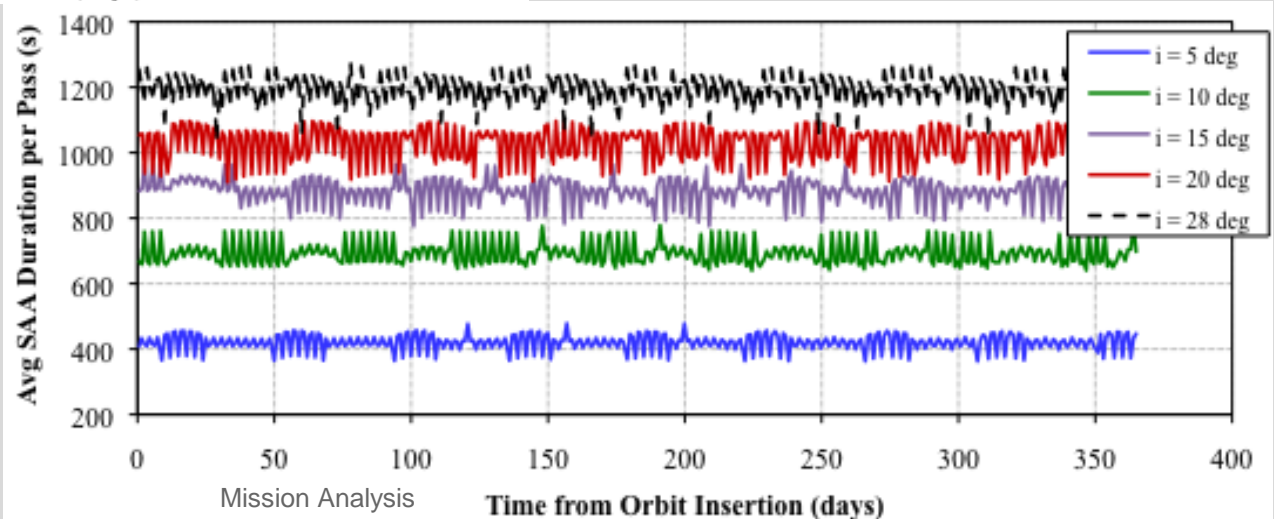
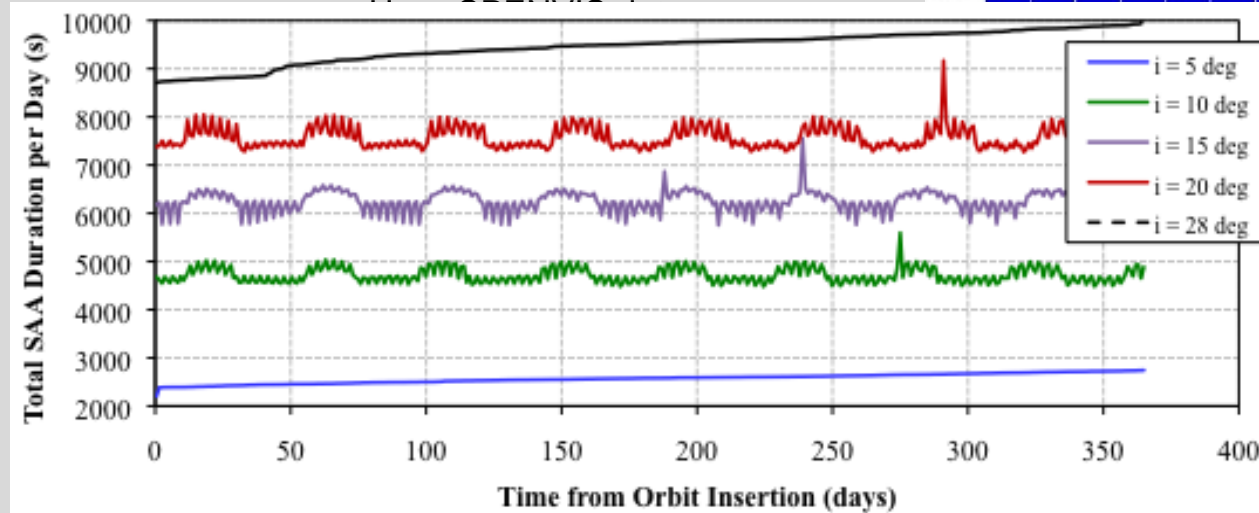
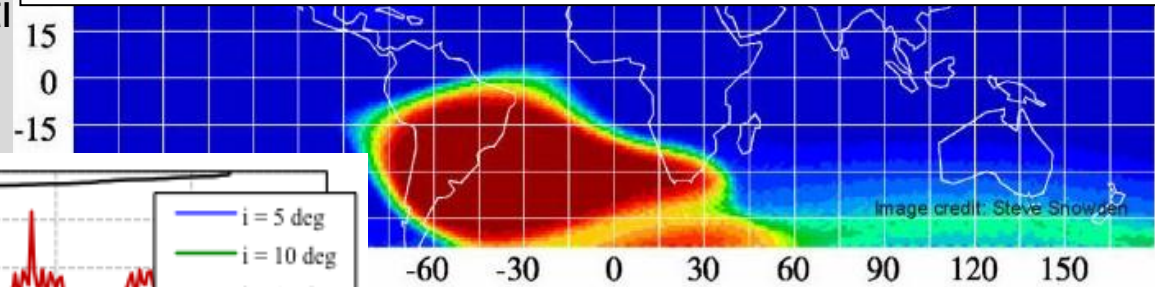
## South Atlantic Anomaly Passes

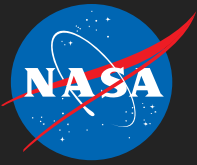
- ◆ Used script provided by Jens Rar
- AXTAR through the South Atlantic

- ◆ Version: 17-June-09

SAA at ~ 560 km

(<http://heasarc.gsfc.nasa.gov/docs/rosat/gallery/display/saa.html>)





# Mission Analysis

## Initial List of Ground Stations

- Initial list of ground stations:

- ◆ ACN (Ascension Island)
- ◆ *AGO (Santiago, Chile)\**
- ◆ *CAN (Canberra, Australia)\**
- ◆ GWM (Guam)
- ◆ *HAW (Kauai, Hawaii)\**
- ◆ *MILA (Merrit Island, Florida)\**
- ◆ *PDL (Ponce de Leon, Florida)\**
- ◆ South Point (Chile)
- ◆ *WGS (Wallops, Virginia)\**
- ◆ Kourou (French Guiana)

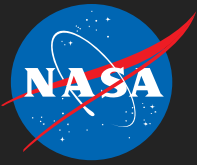
*\* denotes options that are included in 28.5° orbital inclination case (not 5° case)*

Other ground stations are valid for both 5° and 28.5° orbital inclinations

*Minimum allowed contact time = 300 s*  
*Minimum dish elevation = 5°*

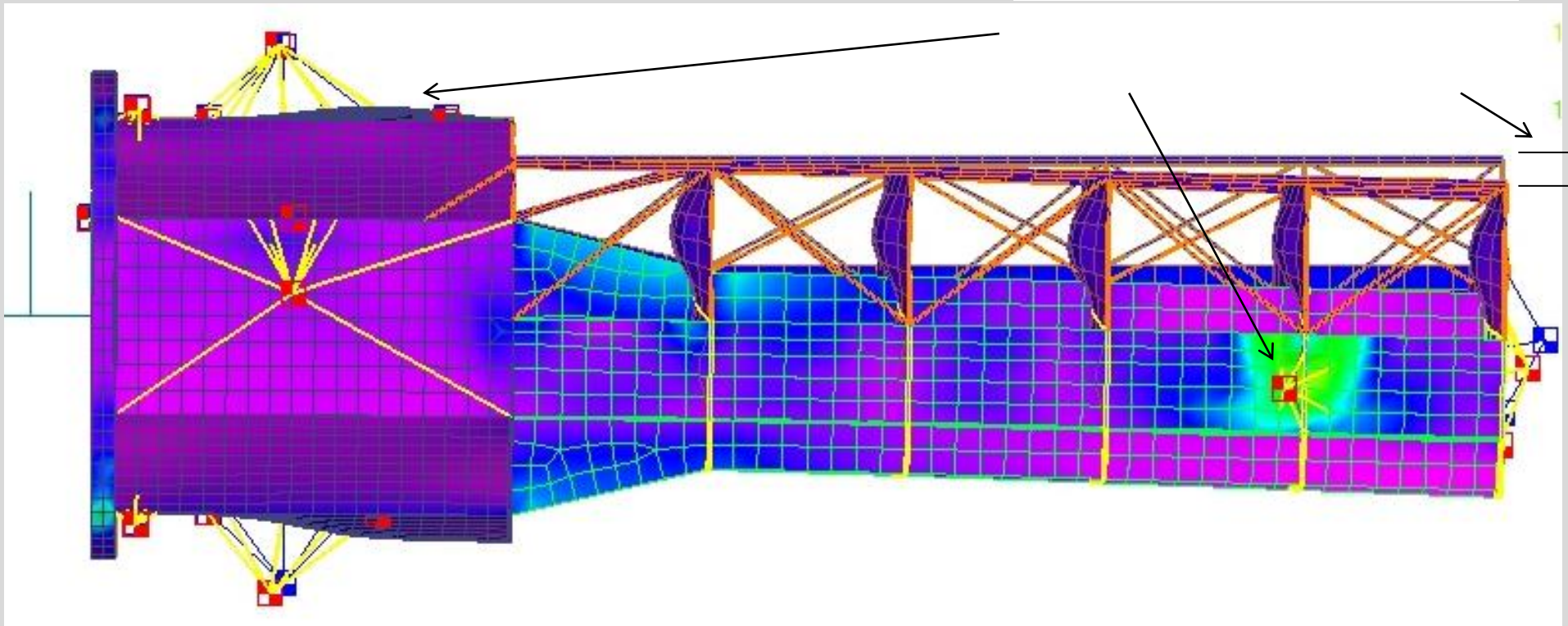


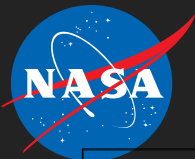




# AXTAR: Structures

Bending displacements < 3 cm





# AXTAR: Avionics

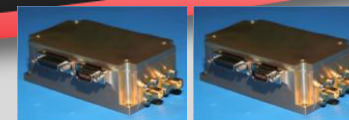
Major Components



Northrop Grumman  
Inertial Measurement Unit LN200  
0.15 deg/sqrHr,  
sufficient for maneuvers

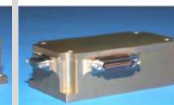
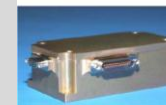


Ball Aerospace  
Star Tracker CT - 602  
4 arc sec accuracy, 5" required



Receiver - can be used stand-alone

Receiver - can be used stand-alone



Interface/Power Controller

Interface/Power Controller



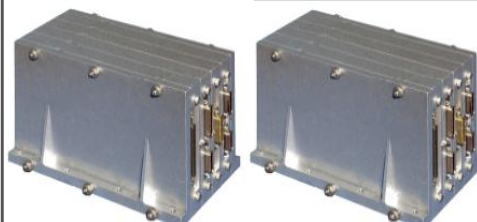
Transmitter

Transmitter

AeroAstro  
S-band Transceiver  
5 W transmitter, able to link TDRSS  
Data rate, 60 kbps



Rockwell Collins Telix  
Reaction Wheel RSI 68-170  
Provides fast slew torque



SpaceMicro Inc.  
Proton 200 Computer  
4 kg each  
Customizable



L3 X-band Transmitter T-728  
20 W, provides high data rate 64 Mbps  
Can download with two links per day  
providing greater ops flexibility



GOCE Magnetic Torquer MT400-2



GOCE Magnetic Torquer MT400-2



GOCE Magnetic Torquer MT400-2

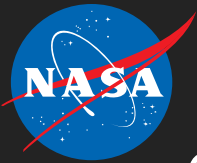
Microcosm MT400-2  
To provide attitude torque authority  
for long observation times  
National Aeronautics and Space Administration



Surrey Satellite Technology.  
High speed Data Recorders  
256 Gbits, 150Mbps

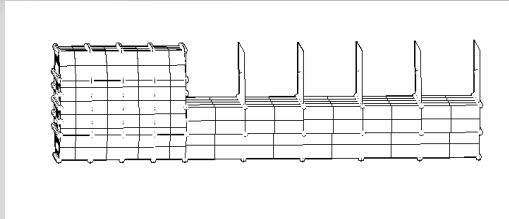


L3 Data Acquisition Unit DTP-503  
32 drivers and 32 inputs, 1553 data interface

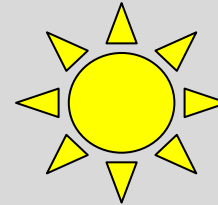
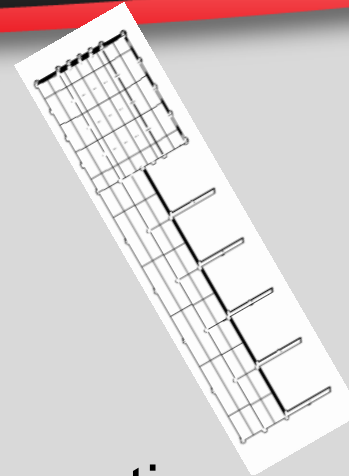
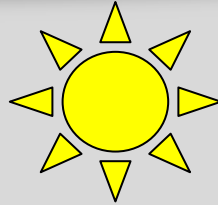


# AXTAR: Thermal

- Cold and Hot Case AXTAR to Sun Orientation



**Cold Case,  
Beta=0°**



**Hot Case, Beta=50°  
Sun Angle = 30°**

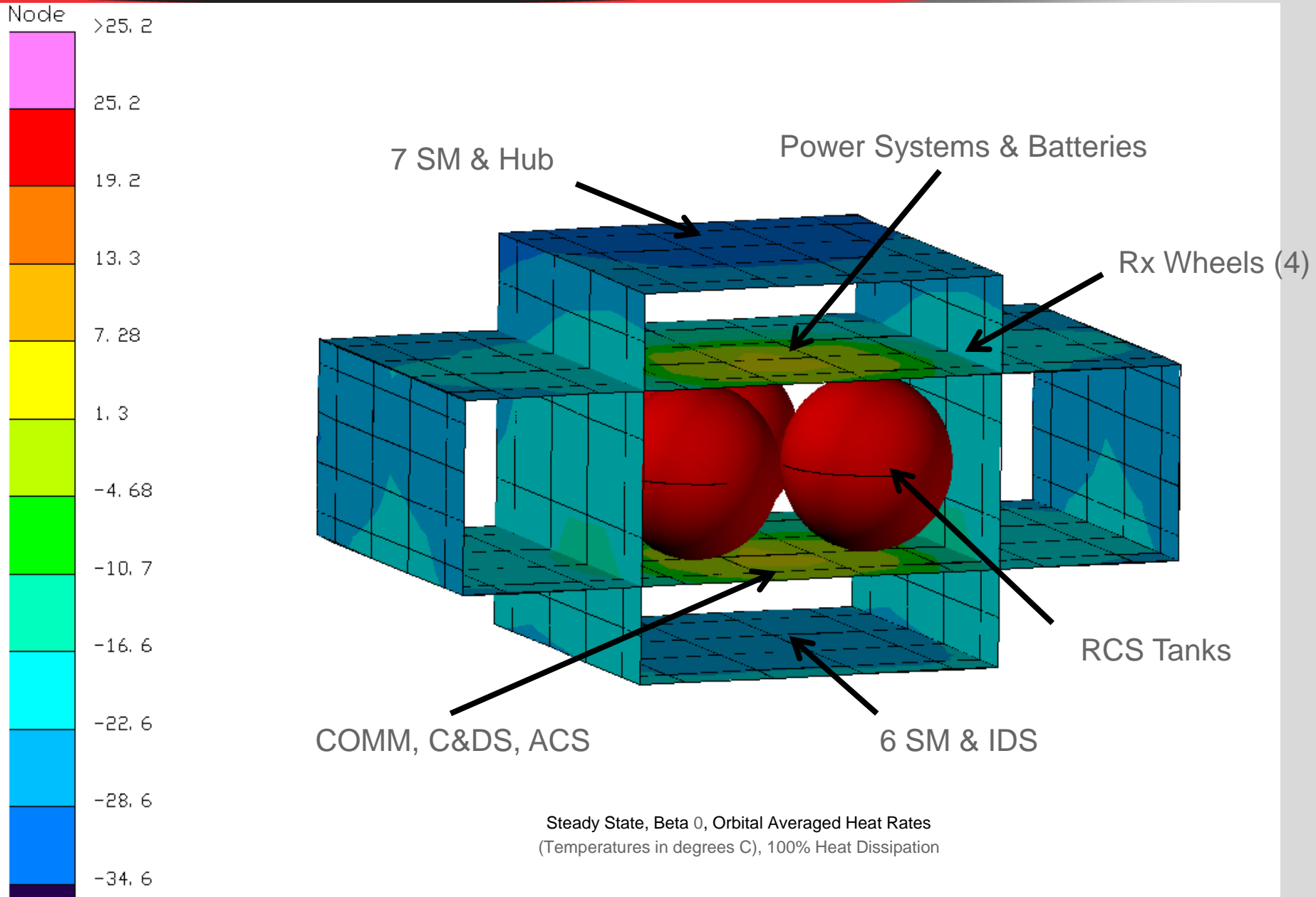
## ◆ Thermal model surface optical properties

	Material	Absorptivity	Emissivity
Spacecraft Bus Internal Surfaces	Black Annodized	.9	.9
Spacecraft Bus External Surfaces	White Paint	.25	.87
Spacecraft Bus Closeouts	White Paint on Beta Cloth Inner Layer, Black Kapton (MLI=5 Layers) $\epsilon^* = .02$	.17 .92	.92 .88
LATA Support Structure	White Paint on Beta Cloth (12 Layers) $\epsilon^* = .004$	.17	.92
LATA Supports	White Paint	.25	.87
LATA Sunshades	White Paint	.25	.87
RCS Tanks	MLI (5 Layers, AIK), $\epsilon^* = .02$	.6	.09



# AXTAR: Thermal

## ◆ Results - Taurus II – Spacecraft Bus - Cold Case





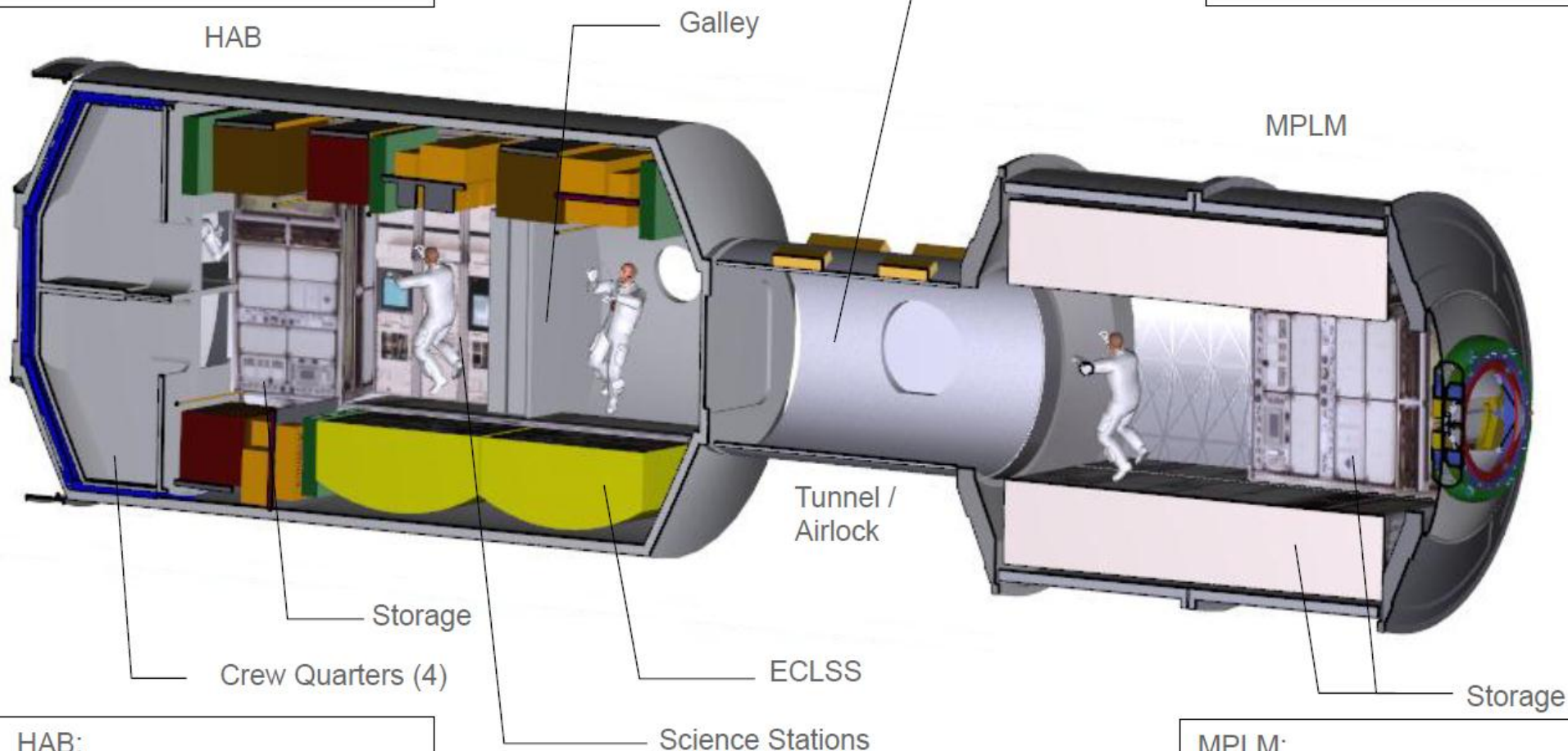


# Deep Space Habitat

500-day DSH:  
Pressurized volume =  $\sim 193 \text{ m}^3$   
Habitable volume =  $\sim 90 \text{ m}^3$

ACO\_Border1-02.png

Service Tunnel / Airlock:  
Pressurized volume =  $\sim 10 \text{ m}^3$   
Habitable volume =  $\sim 9 \text{ m}^3$

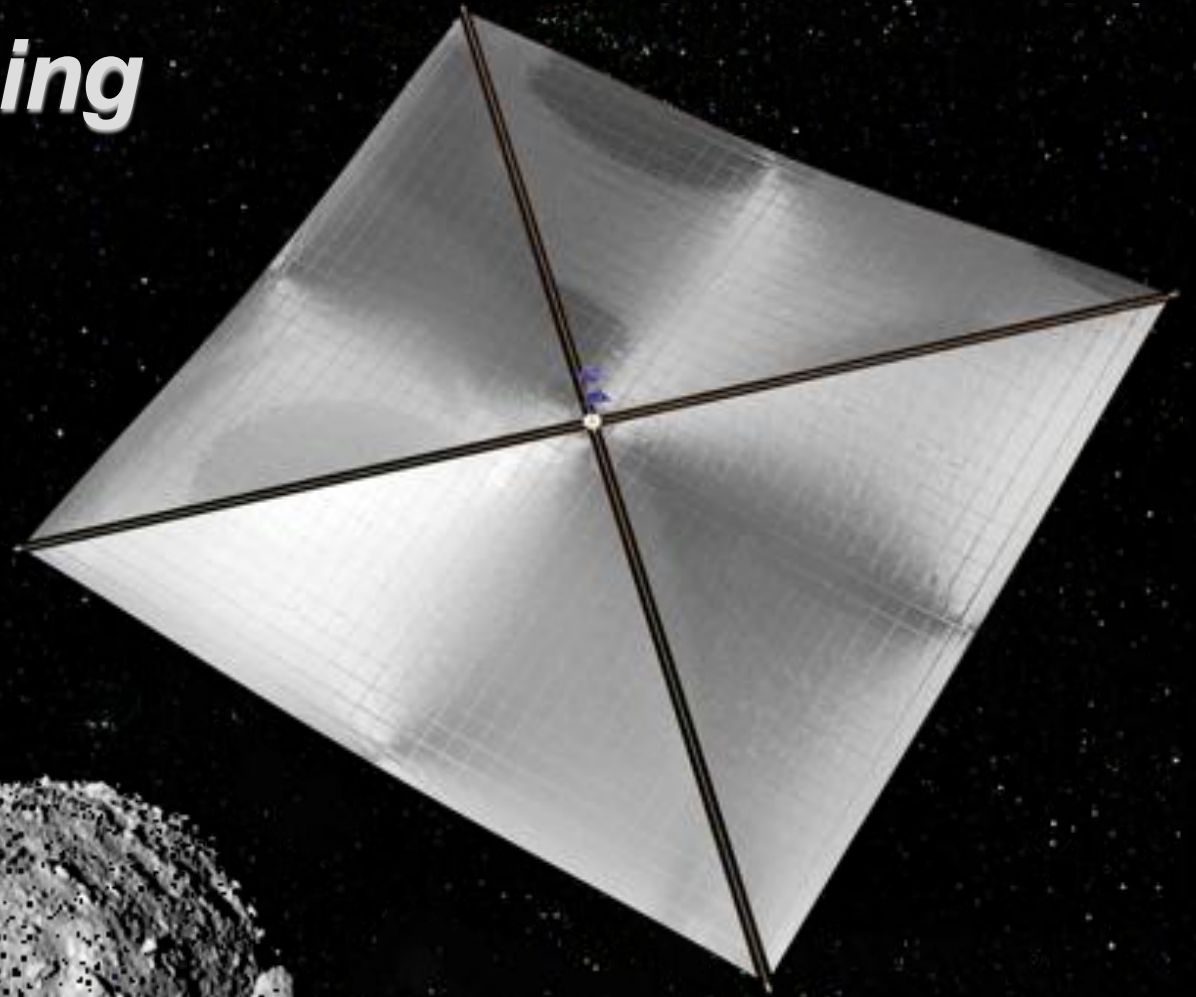


HAB:  
Pressurized volume =  $\sim 107 \text{ m}^3$   
Habitable volume =  $\sim 56 \text{ m}^3$   
Stowage volume =  $\sim 16 \text{ m}^3$

MPLM:  
Pressurized volume =  $\sim 76 \text{ m}^3$   
Habitable volume =  $\sim 25 \text{ m}^3$   
Stowage volume =  $\sim 33 \text{ m}^3$



# ***Multiple NEO Rendezvous Using Solar Sails***



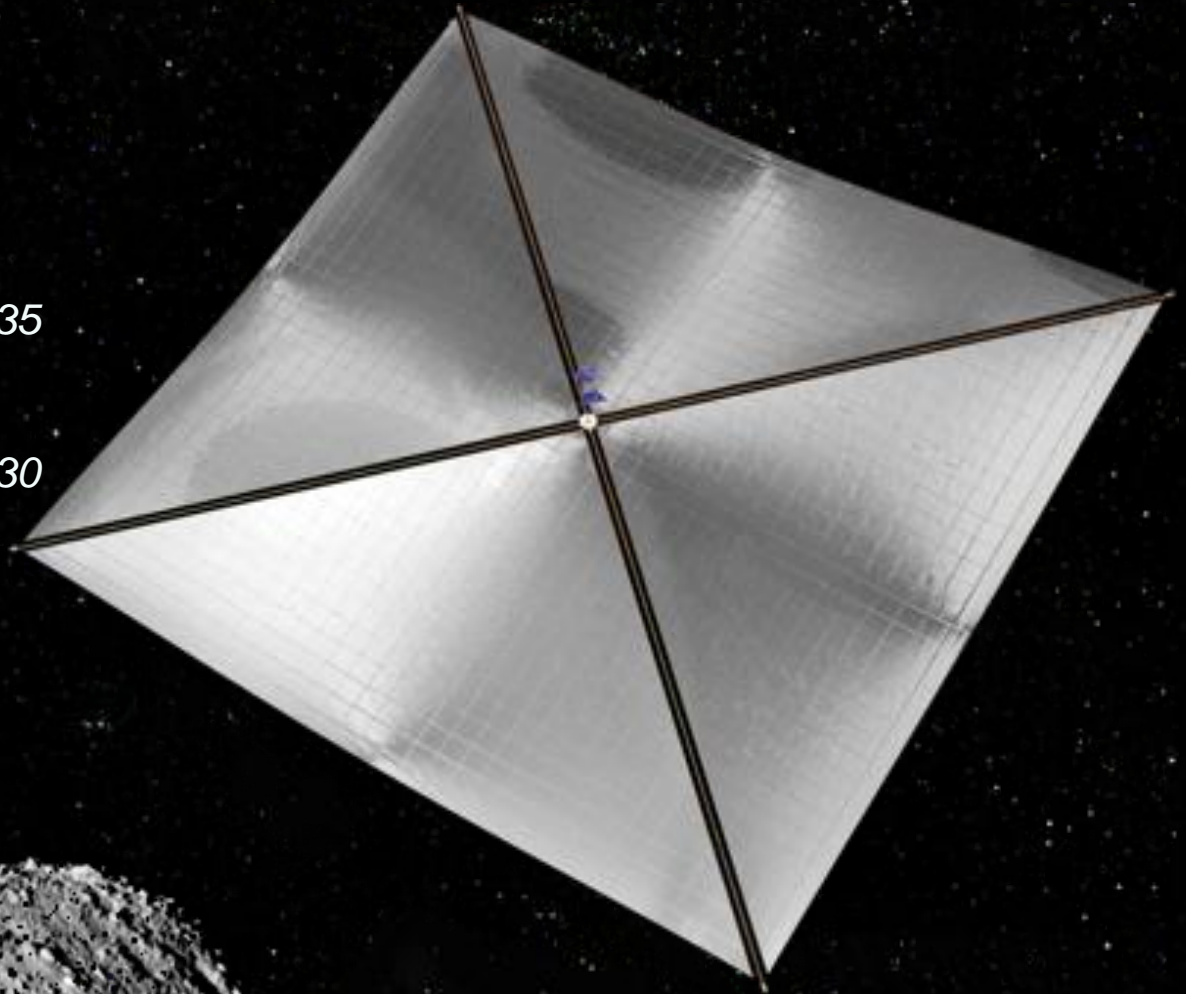
Assess the feasibility of using solar sail propulsion to enable a robotic precursor that would survey multiple Near Earth Objects (NEOs) for potential future human visits

## **Solar Sail Asteroid Rendezvous Mission:**

**Departure:** Aug 2017

### **Candidate asteroids visited:**

<u>Period</u>	<u>NEO</u>	<u>Date</u>	<u>Observation</u>
days	1999 A010		Mar 2019 35
	Apophis	Dec 2021	30 days
days	2001 QJ142		July 2023 30

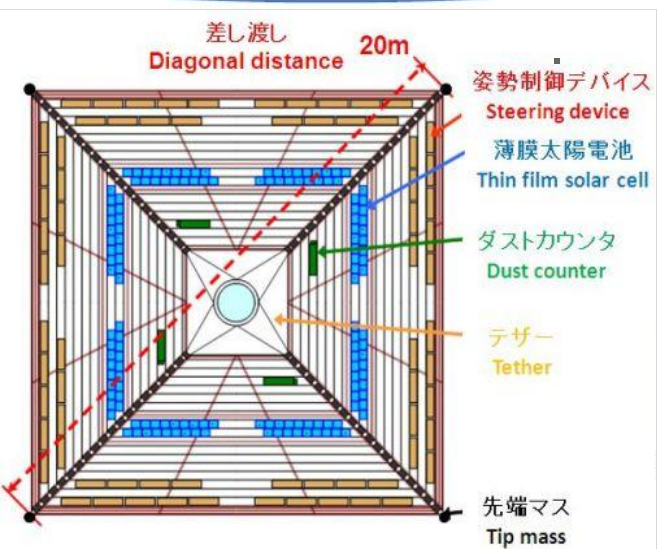
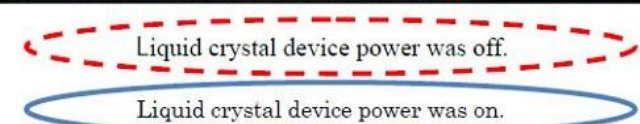
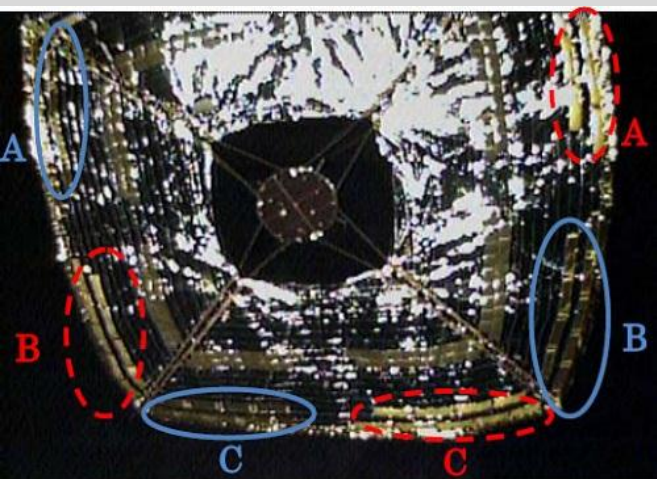
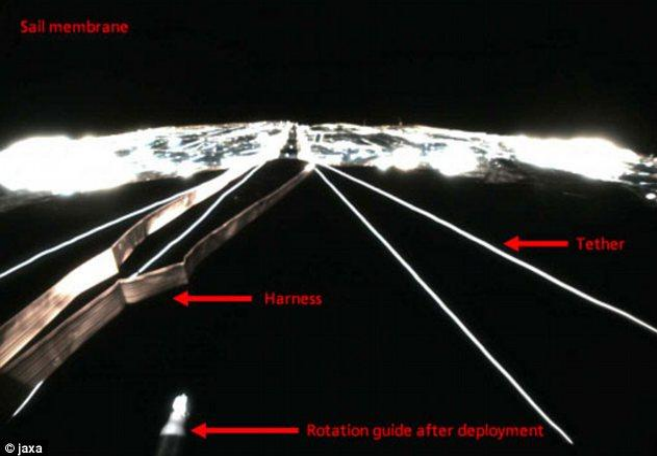


**Solar Sail Spacecraft Launch Mass:**  
328.6 kg

**Mass at destination:**  
228.4 kg

**Cost:**  
\$175M, plus launch vehicle and ops





# Interplanetary Kite-craft Accelerated by Radiation Of the Sun (IKAROS)

- IKAROS was launched on May 21, 2010
- The Japan Aerospace Exploration Agency (JAXA) began to deploy the solar sail on June 3.
- IKAROS has demonstrated deployment of a solar sailcraft, acceleration by photon pressure and attitude control
  - Deployment was by centrifugal force
  - Sail membrane is 7.5 mm thick

Configuration / Body  
Diam.

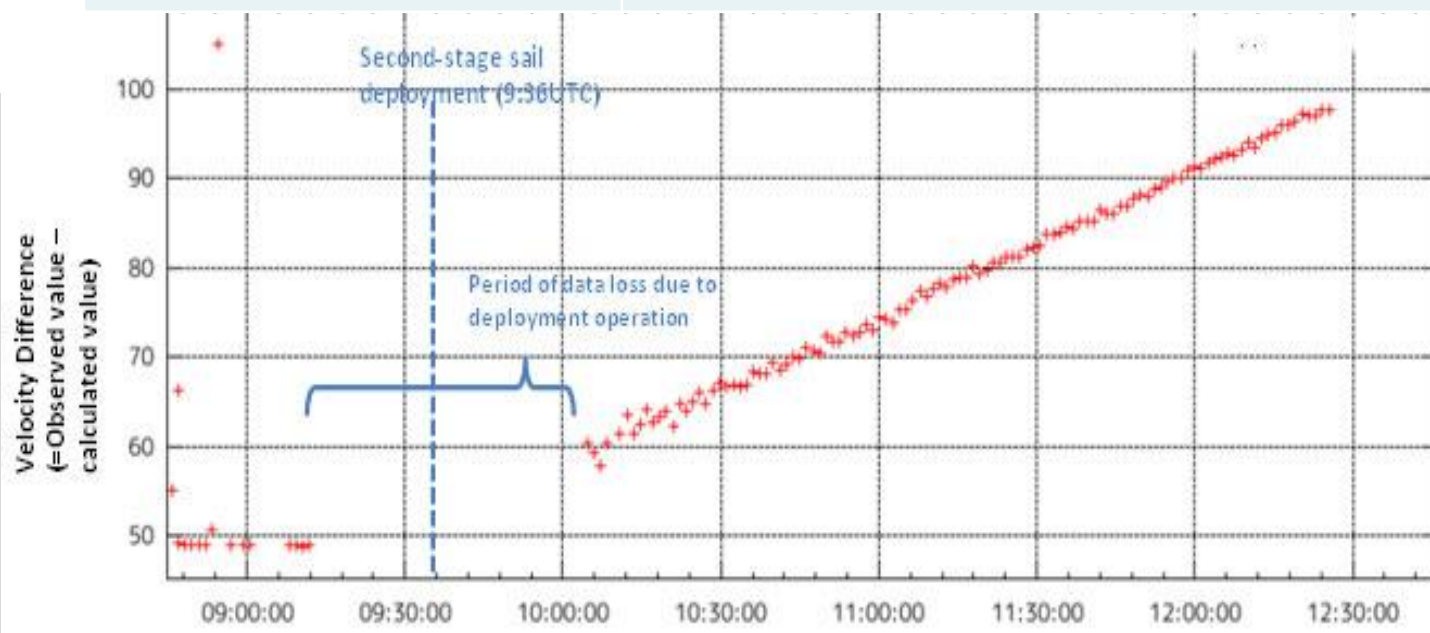
1.6 m x Height 0.8 m (Cylinder shape)

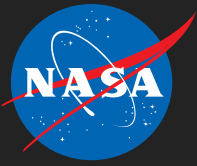
Configuration / Membrane

Square 14 m and diagonal 20 m

Weight

Mass at liftoff: about 310 kg

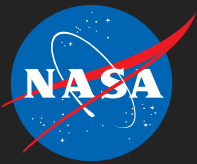




# Space Launch: Advancing the Legacy of Human Exploration



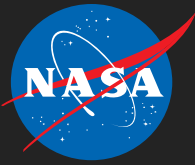




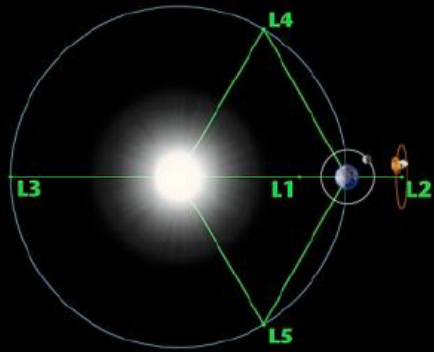
# SLS is a National Asset







# SLS Will Open Up the Inner Solar System for Human Exploration



## High-Earth Orbit (HEO)/Geosynchronous-Earth Orbit (GEO)/Lagrange Points:

- Microgravity destinations beyond LEO
- Opportunities for construction, fueling, and repair of complex in-space systems
- Excellent locations for advanced space telescopes and Earth observatories

## Earth's Moon:

- Witness to the birth of the Earth and inner planets
- Has critical resources to sustain humans
- Significant opportunities for commercial and international collaboration



## Mars and Its Moons, Phobos and Deimos:

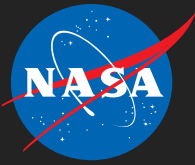
- A premier destination for discovery: Is there life beyond Earth? How did Mars evolve?
- True possibility for extended, even permanent, stays
- Significant opportunities for international collaboration
- Technological driver for space systems



## Near-Earth Asteroids:

- Compelling science questions: How did the Solar System form? Where did Earth's water and organics come from?
- Planetary defense: Understanding and mitigating the threat of impact
- Potential for valuable space resources
- Excellent stepping stone for Mars

***Increasing Our Reach and Expanding Our Boundaries***



# The Space Launch System Objectives

## ◆ **Safe: Human-Rated**

- Loss of Crew/Loss of Mission: TBR

## ◆ **Affordable**

- Constrained budget environment, with no planned escalation
- Maximum use of common elements and existing assets, infrastructure, and workforce

## ◆ **Initial capability: 70 tonnes (t), 2017–2021**

- Serves as primary transportation for Orion and exploration missions
- Provides back-up capability for crew/cargo to ISS

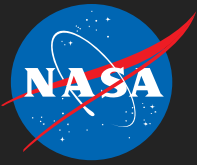
## ◆ **Evolved capability: 130 t, post–2022**

- Offers large volume for science missions and payloads
- Modular and flexible, sized to mission requirements

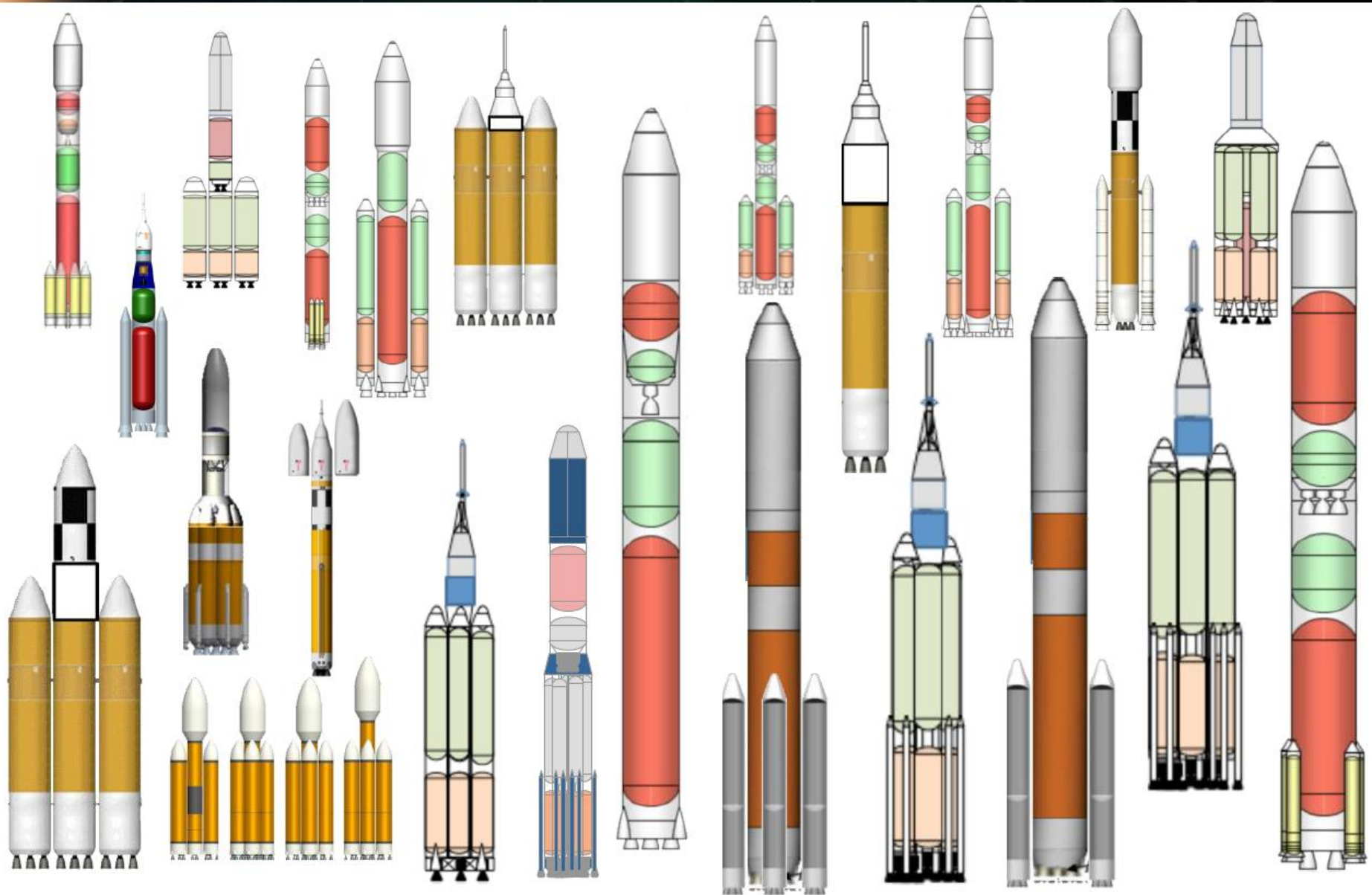


***SLS First Flight in 2017***





# Many Solutions: One Affordable Answer

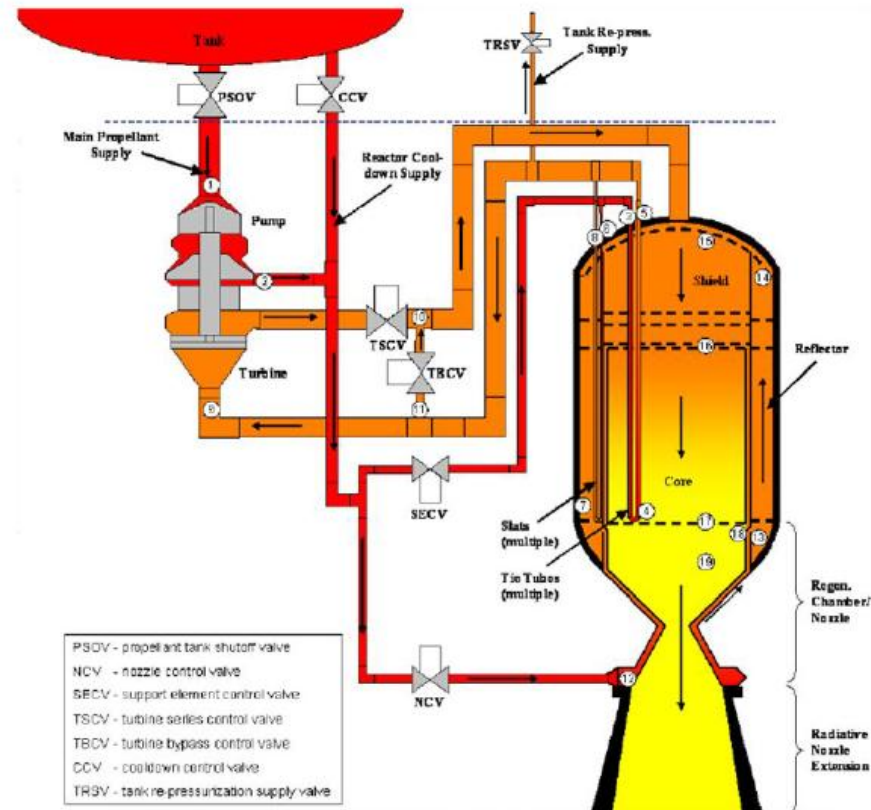


*"This enterprise is not for the faint of heart."  
—Wayne Hale*



# AES Nuclear Cryogenic Propulsion Stage

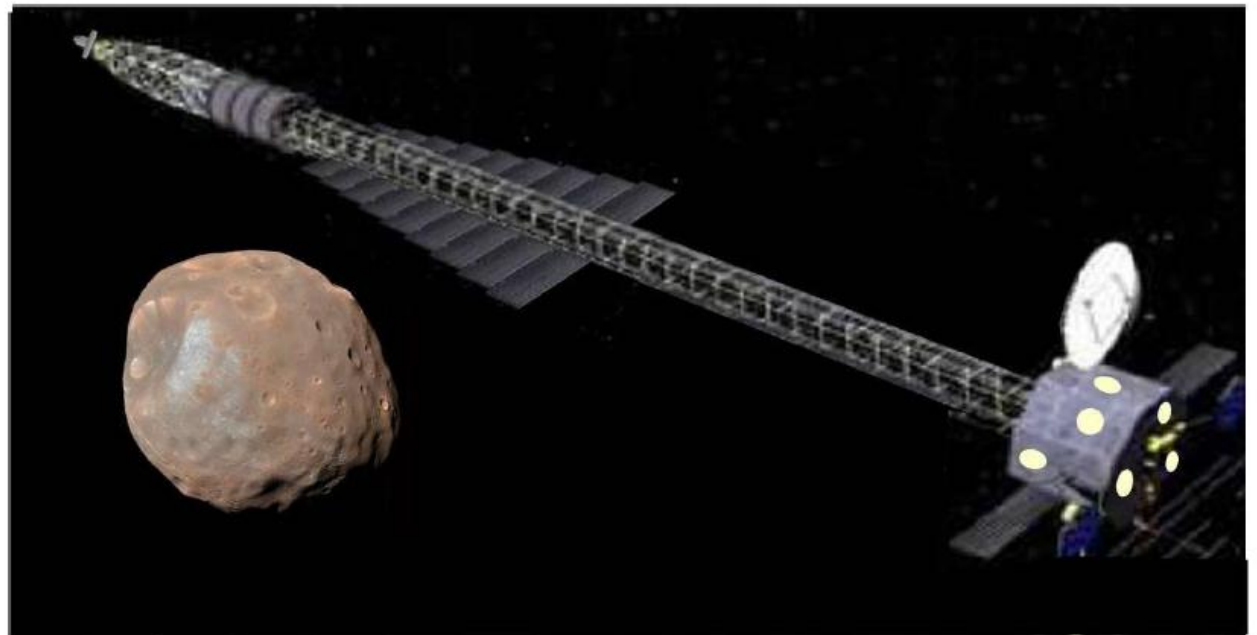
- ◆ MSFC led activity to establish viability of Nuclear Thermal Propulsion for future NASA exploration missions
- ◆ ED04 is supporting mission architecture analysis and vehicle concept performance trade studies



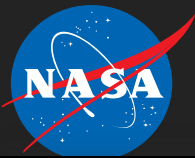


# Fission Fragment Rocket Engine Mission Concept

- ◆ MSFC (EV) led NIAC study to define technology characteristics and evaluate mission concepts for dusty plasma Fission Fragment propulsion technology
- ◆ ED04 is performing mission analysis and spacecraft concept design







# Example: Cryostat

## CRYOSTAT Mission Overview

### DESCRIPTION

- This project will demonstrate the technologies needed to store, monitor, access, pre-position and transfer cryogenic propellants for large cryogenic propellant storage and transfer systems that will support future space mission and commercial market opportunities

### APPROACH

- Critical technologies are demonstrated in one mission utilizing one vehicle

### APPLICATIONS

- Human exploration missions beyond LEO utilizing:
  - Large cryogenic stages w/ long duration space exposures
  - Propellant transfer for the earth departure stages (EDS)
- Supporting infrastructure for commercial space options (e.g., for satellite servicing, propellant transfer, refueling depots, tourism, etc.)

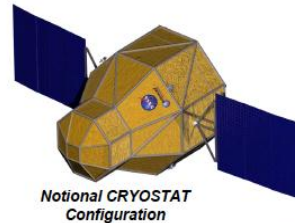
### BENEFITS

- Enabling large cryogenic propulsion stages for Human exploration
- Options for use of commercial operations to support explorations missions (through use of multiple propellant transfers)

### TECHNOLOGY ELEMENTS

- Tank Thermal Control
- Tank Pressure Control
- Cryogenic Propellant Transfer
- Liquid Acquisition
- Mass Gauging
- Leak Detection

### CONFIGURATION



Notional CRYOSTAT Configuration

## CRYOSTAT Concepts

### CPS-Lite Maximum Size (on Falcon 9 Capability)

Length: 4.6 m  
Dia.: 4 m  
LH2 Mass: 316 kg  
LOX Mass: 2000 kg  
CFM System: 3816 kg  
Bus: 3020 kg  
Total Mass: 6836 kg

### CPS-Lite Minimum Size (Based on 2 Month Mission)

Length: 4.2 m  
Dia.: 2 m  
LH2 Mass: 250 kg  
LOX Mass: 580 kg  
CFM System: 2350 kg  
Bus: 1300 kg  
Total Mass: 3650 kg

### CPS-Pathfinder (2 Month Mission)

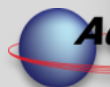
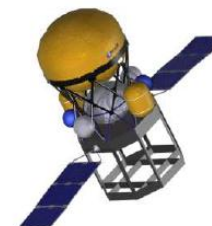
Element	Mass
LH2	250 kg
Total CFM Payload	791 kg
Spacecraft Bus	471 kg
Launch Mass	1262 kg

Spacecraft Size  
Length = 2.4 m  
Dia. = 1.9 m



CFM System

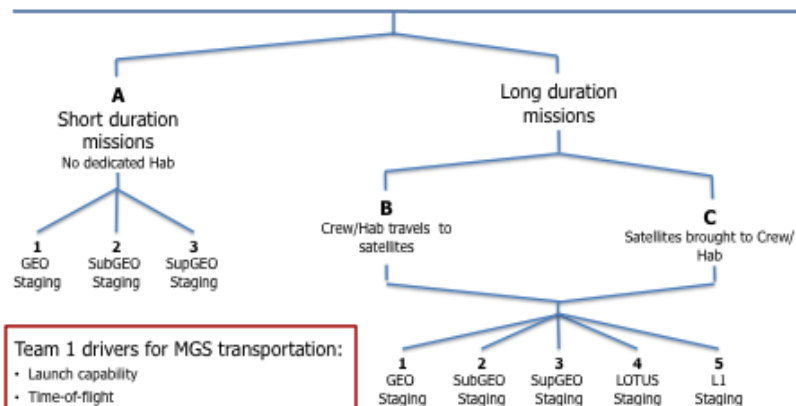
Spacecraft Bus





# Example: Manned GEO Servicing

## DARPA Mission architecture considerations



### Team 1 drivers for MGS transportation:

- Launch capability
- Time-of-flight
- Fuel usage
- Prepositioned elements
- Manned element considerations
- Satellite considerations

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## DARPA Potential launch vehicles for MGS missions (1 of 2)



1 – KSC ELV performance, 200 km  
2 – SpaceX Falcon Heavy Quoted Estimate  
3–30 new X 130 mm insertion, 28.5 degrees, no margin

Planned



Launch Vehicle	Falcon 91	Falcon 9 Heavy2	Atlas 5011	Atlas 4011	Atlas 5411	Atlas 5511	Delta IV Heavy1	In-line Shuttle C3	HEFT SDV3
LEO payload (kg)	9,115	32,000	8,140	9,605	15,930	17,415	23,660	79,900	106,600
GTO payload (kg)	3,475	19,500	3,860	4,740	7,850	8,540	12,575	~37,800	51,395
GEO payload (kg)	~1,750	~9,750	~1,930	~2,375	~3,925	~4,270	6,160	~21,735	29,556

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## DARPA Potential launch vehicles for MGS missions (2 of 2)



Launch Vehicle	DIVH w/ACES US	Atlas V Phase 2	Atlas V Phase 2 w/Ares 1 2nd stage/ACES 3rd	Atlas V Phase 3 w/Ares 1 2nd stage/ACES 3rd	Ariane 5 ECA (AS w/DWIT cryo US)	Proton K	Proton M
LEO payload (kg)	35,000	77,900	80,000	120,000	20,000	20,800	22,000
GTO payload (kg)	19,500	43,200	~40,000	~60,000	10,500 (12,000 with SEC8 upgrade)	5,100	6,000
GEO payload (kg)	~9,750	24,100	~23,000	~34,500	~5,250	2,600	3,500

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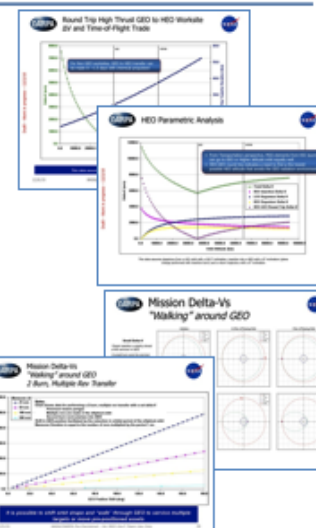
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## DARPA Astrodynamics mission architecture trades



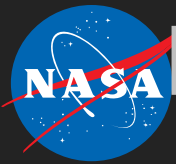
- Radiation environment,  $\Delta V$  vs. orbital altitude:
  - EVA radiation environment improves above GEO
  - Elements transiting from LEO to GEO or HEO-65k require minimal increase in fuel usage
- Chemical propulsion vs. electric propulsion:
  - Chemical propulsion provides lower time-of-flight, electric propulsion provide better fuel economy
- Round trip  $\Delta V$  and time-of-flight, LEO to GEO/HEO-65k
- Maneuvering within GEO:
  - Relevant to ability to reach multiple satellites with either rapid response (1 day) or fuel-efficient response (weeks)



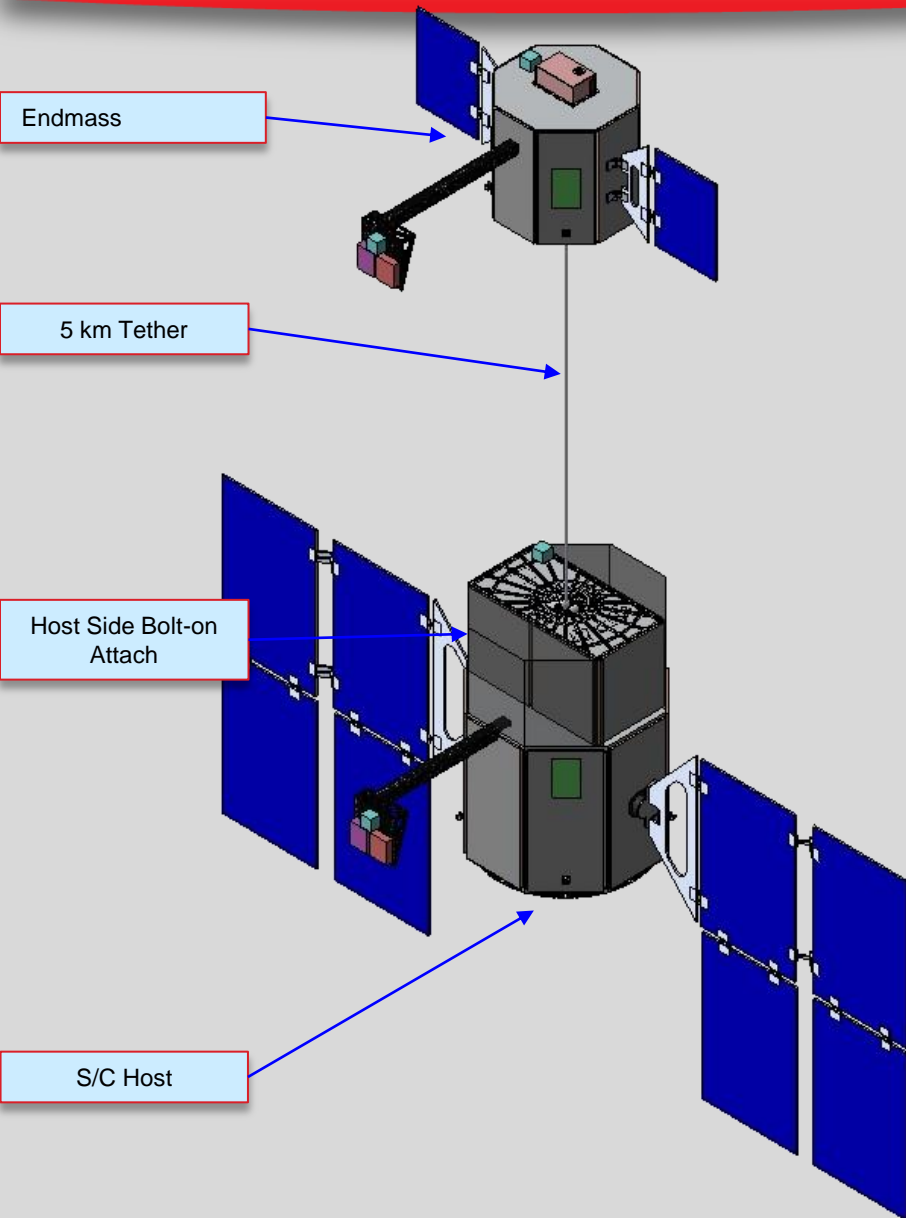
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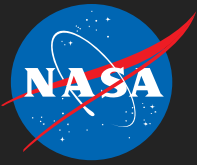
# Propel: Propulsion using Electrodynamics



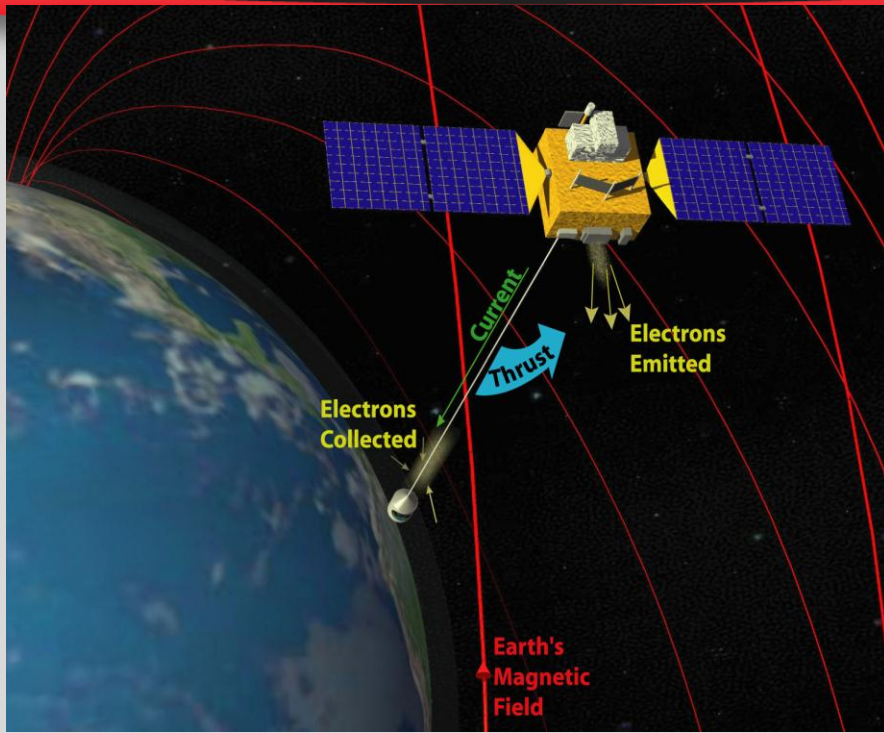
PropEI will demonstrate **robust and safe** electrodynamic tether propulsion in Low Earth Orbit to enable multiple Space Science, Exploration and Space Utilization Missions for a variety of users

- ◆ LEO propulsion and station-keeping without the use of fuel
- ◆ Multipoint *in situ* LEO plasma measurements
- ◆ Enabling technology for more ambitious reusable tether upper stages
- ◆ Critical demonstration for MW power generation and propulsion at Gas Giants





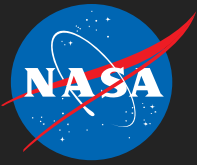
# How Does Propel Work?



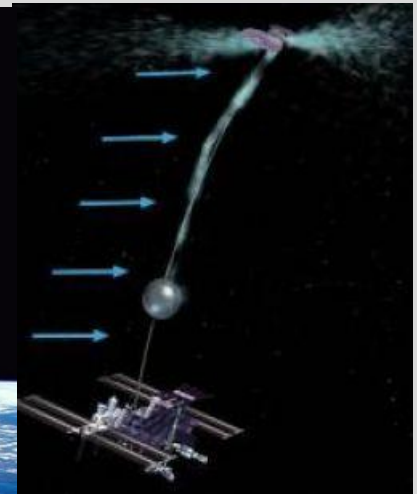
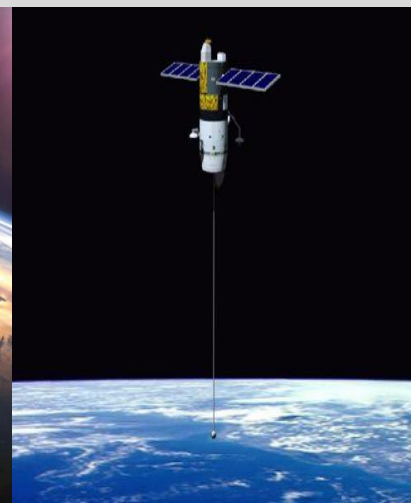
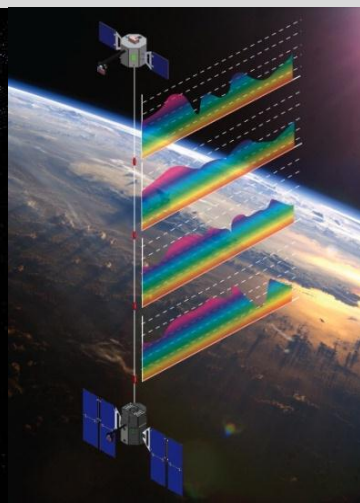
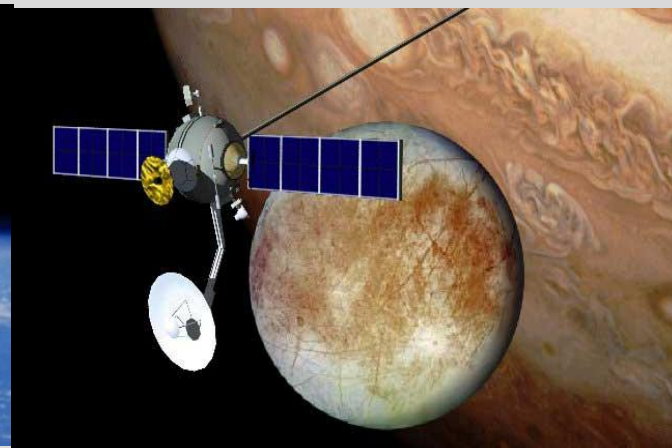
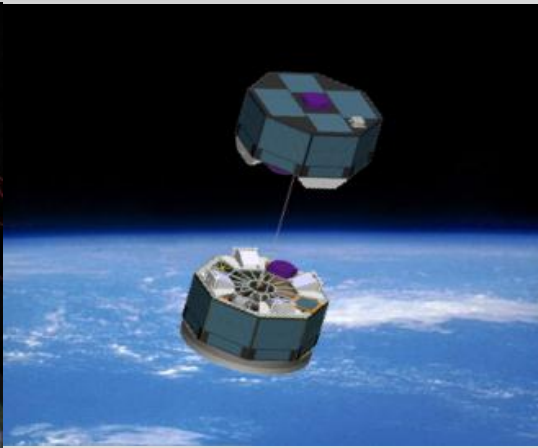
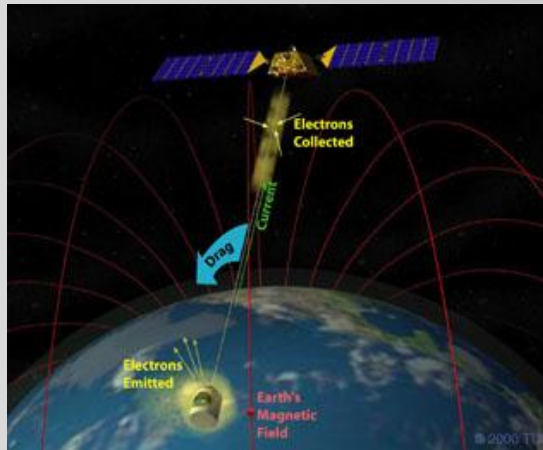
An **Electrodynamic Tether (EDT)** is essentially a long conducting wire extended from a spacecraft. Gravity will tend to orient the tether in a vertical position. If the tether is orbiting around the Earth, it will be crossing the Earth's magnetic field lines at orbital velocity (7-8 km/s!). The motion of the conductor across the magnetic field induces a voltage along the length of the tether.

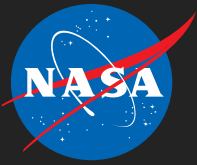
- ◆ An EDT can produce thrust by collecting electrons from the local plasma at one end of the tether and expelling them back into the plasma at the other end; the voltage drives a current along the tether
- ◆ This current interacts with the Earth's magnetic field to cause a Lorentz force ( $\mathbf{J} \times \mathbf{B}$ ) either parallel or antiparallel to the spacecraft's velocity
- ◆ The resulting electrodynamic force is controlled and used for station-keeping, boost, deboost and to change a spacecraft's inclination





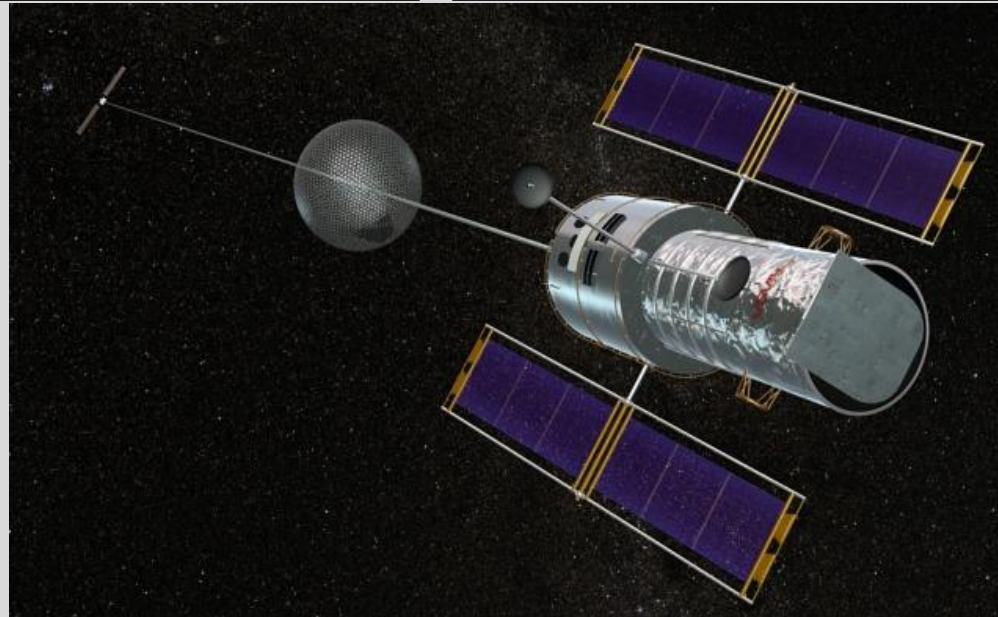
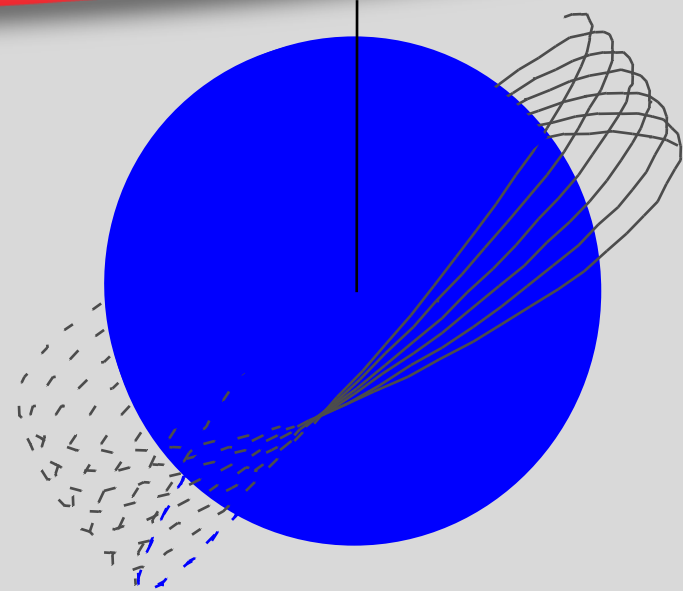
# MISSIONS ENABLED BY PROPEL

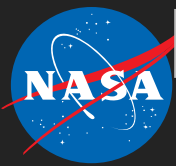




# Inclination and Altitude Change

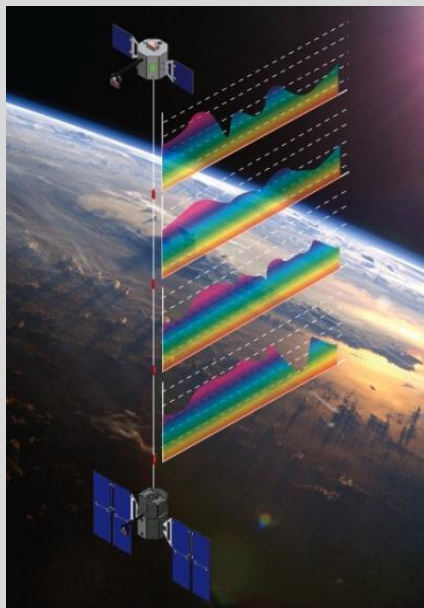
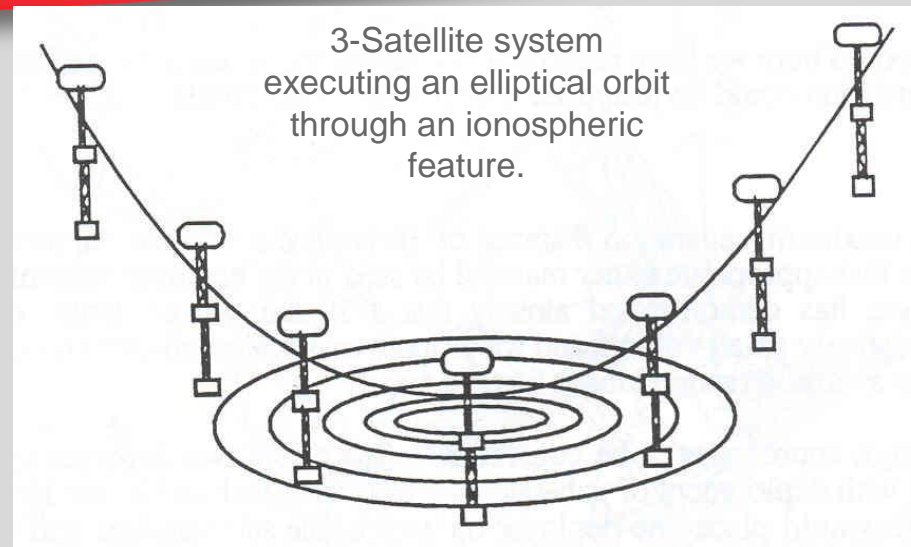
- ◆ Cape Canaveral launch sites and Vandenberg launch sites cannot reach the same orbital inclinations due to launch azimuth constraints.
- ◆ With an electrodynamic tether tug in LEO, satellites could be launched into another inclination and then “towed” to the proper inclination.
- ◆ LEO tether tug could also reboost or change multiple spacecrafts’ orbital elements
- ◆ Important capability for high-value national assets.



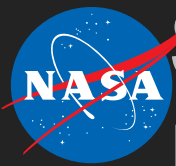


# Multipoint Ionospheric Science

- ◆ Three or more instrumented satellites tethered with a separation of 10km.
- ◆ Each subsatellite deploys itself from the central spacecraft; one upward and one downward
- ◆ Baseline elliptical orbit with <140km perigee and optional electrodynamic rebost for sustained low-altitude flight

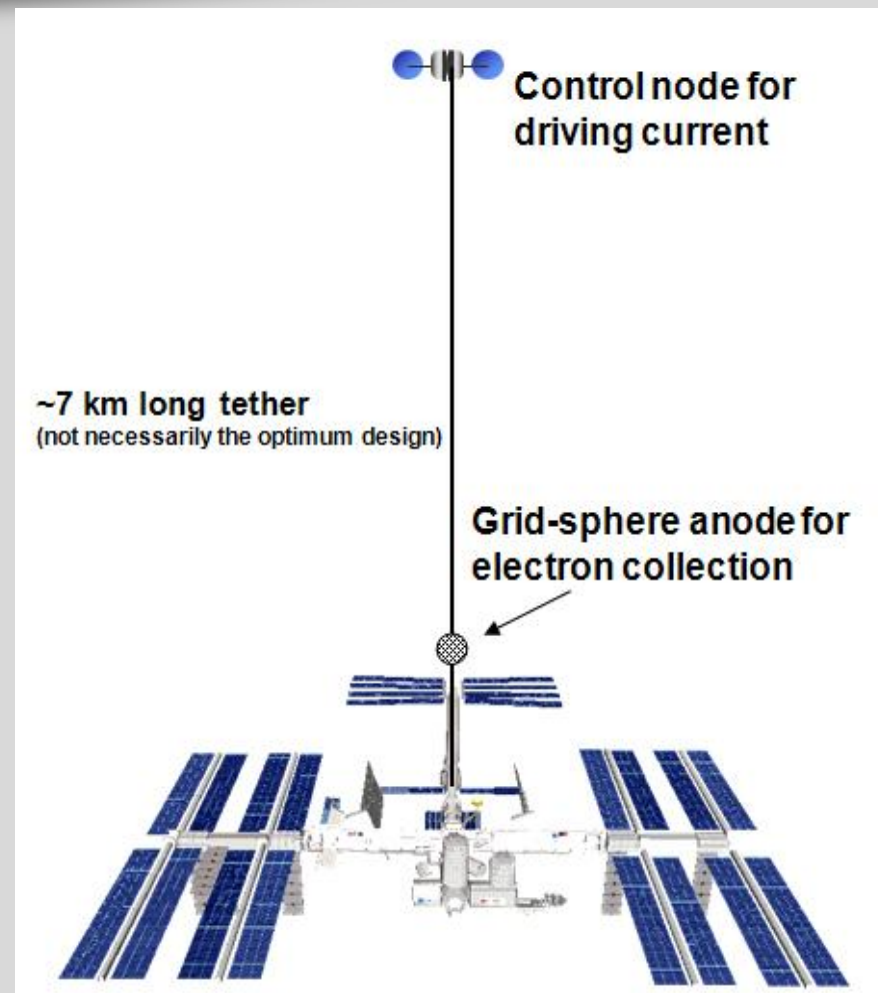
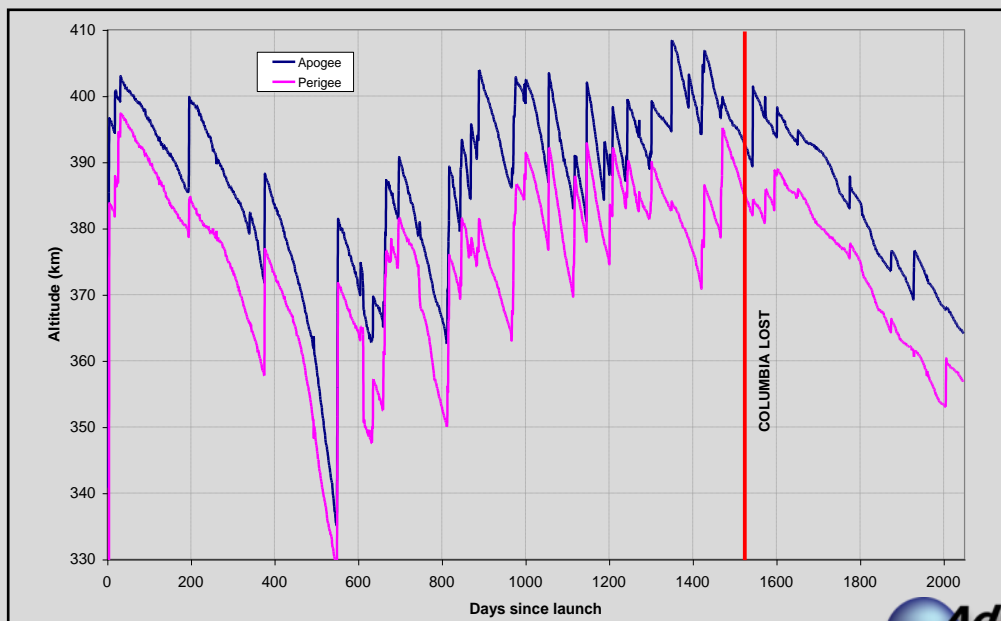




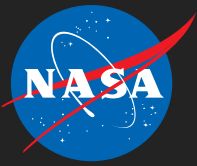


# Station Keeping or Reboost of Space Platforms

- ◆ Atmospheric drag causes the ISS orbit to continuously decay.
- ◆ Russians supply fuel for propulsive reboost.
- ◆ An electrodynamic tether could be used to reboost the ISS orbit without consuming propellant.
- ◆ The tether would also passively stabilize the station configuration (gravity-gradient).
- ◆ Safety and value of ISS would increase.

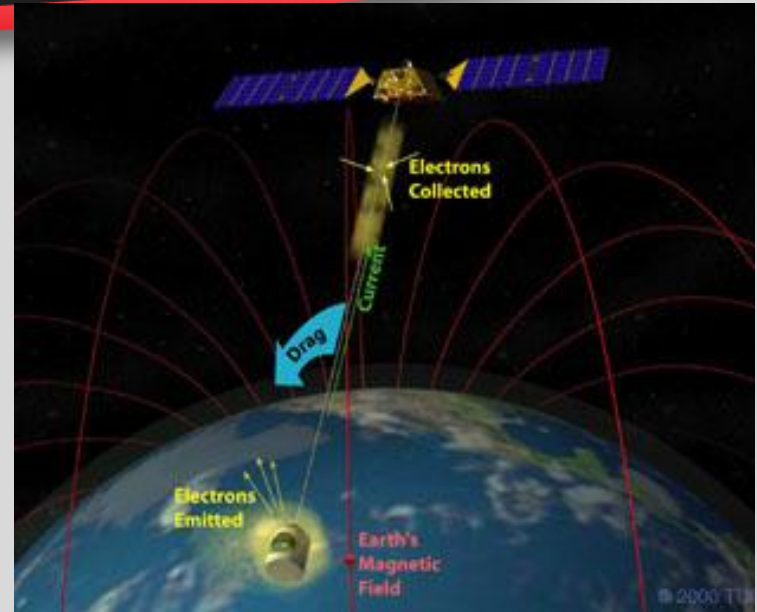






# Orbital Debris Mitigation — "Terminator Tether"

- ◆ Dead satellites can remain in orbit for extended periods of time and pose a debris and collision threat.
- ◆ An electrodynamic tether can be deployed from the spacecraft after it "dies" and will generate drag forces that will cause the spacecraft to deorbit.
- ◆ Unlike propulsive deorbit, the host spacecraft does not need to be operating or have attitude control—the tether generates the power and stability it needs.
- ◆ Debris populations can be reduced significantly.



# Jovian Electrodynamic Capture

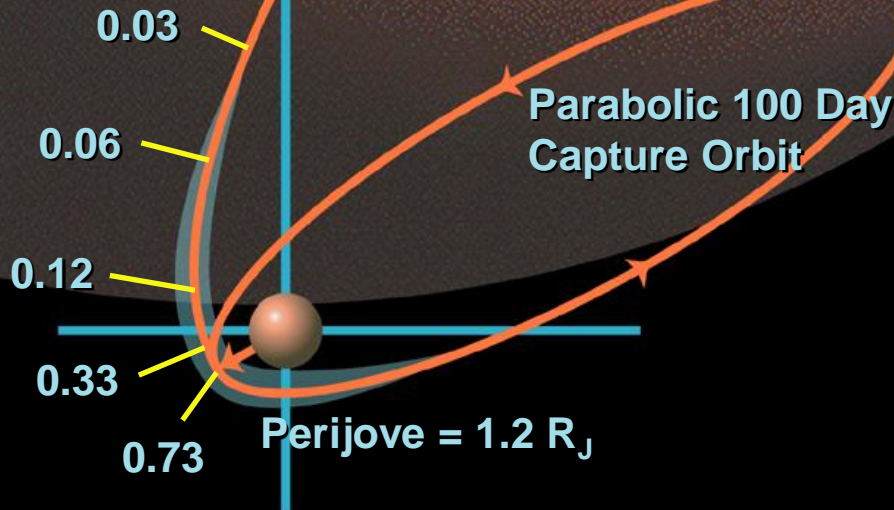
## Tether Applications

- Deboost for Capture
- Orbit Adjustment
- Electric Power

$V_{\infty} = 5 \text{ km/sec}$

Hyperbolic Intercept

Electrodynamic  
Decay Region  
( $\Delta V$  in km/sec)



(0.5 km/sec  $\Delta V$   
required for capture)

## Tether System

- Spacecraft Payload Mass 500kg
- 10km Conducting Tether
- Tether Resistance:  $96\Omega$
- Plasma emitter at each end
- Propulsion Mass Budget

– Tether	98kg
– Emitter Expellant	22kg
– Deployer and Controls	$\leq 128\text{kg}$
– Total	$\leq 240\text{kg}$